



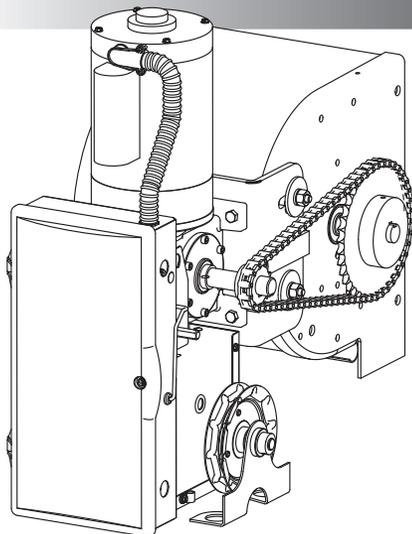
GCL-GH™

Heavy Duty Operator

HOIST

111837.501539 06-12

WITH EXCLUSIVE FEATURES: **Multivolt®**
EZ Limit®



PROPER APPLICATION

Door Type	Operator Type	HP/Max Door Weight
Sectional (All Types)	Hoist (Side/ Centermount)	1/2HP = 1310 lbs. 3/4HP = 1450 lbs.
Rolling Steel (All Types)	Hoist (Front of Hood or Wall Mount)	1HP = 1650 lbs. 3HP = 3696 lbs.

NOT FOR RESIDENTIAL USE

This Installation Manual provides the information required to install, troubleshoot and maintain a GCL-GH™ Commercial/Industrial Door Operator.

Table of Contents

Section 1	How to use this manual	1.1	Section 7	Special Operational Features	7.1-7.2.
Section 2	Safety Information & Instructions	2.1		Operator Cycle Count	7.1
Section 3	Critical Installation Information	3.1-3.3		GDO & Display Firmware	7.1
Section 4	Installation	4.1-4.5		Operator Type	7.2
	Rolling Steel Front	4.1	Section 8	Troubleshooting	8.1-8.5
	Rolling Steel Wall Mount/Side Mount	4.2		Display Operation	8.1
	(Chain Couple)	4-3-4.4		Error Codes	8.1-8.2
	Manual Handwheel/Release Cord	4.5		Run Codes	8.2-8.3
	Optional Clutch	4.6		LED Indicators	8.4
Section 5	Wiring	5.1-5.8		Safe-T-Beam® Self-Diagnostic Troubleshooting Chart	8.5
	Line Voltage Wiring	5.1	Section 9	Service & Maintenance	9.1
	Low Voltage Control Wiring	5.2		Periodic Maintenance Schedule	9.1
	External Wire Diagram	5.3	Section 10	Appendices	10.1-10.16
	Wall Control	5.4		Appendix A	10.1-10.9
	Interlock Switches	5.5		Operator Parts Breakdown	10.1
	Monitored Photocell Device Wiring	5.6		Wall Mount Kit (Chain Couple)	10.2
	Sensing Edge Switch	5.7		Hoist Shafts Parts Breakdown	10.3
	External Radio (Optional)	5.8		Motor Options	10.4
	Connecting Motor/Safety Instructions	5.9		Brake/Release Assemblies	10.5
Section 6	Operator Setup Procedures	6.1-6.9		Base Electric Box Parts Breakdown	10.6
	Setting Close Direction	6.2		Electric Box Layout	10.7
	Setting Braking Rate	6.3		Appendix C	10.8
	Setting Travel Limits	6.4		Screw Terminal Assignments	10.8
	Setting Up Limit Overrun	6.5		Appendix D	10.9-10.10
	Setting Down Limit Overrun	6.6		Run Codes	10.9
	Setting Open & Close Modes	6.7		Error Codes	10.10-10.11
	(Optional) Transmitter Programming	6.8	Section 11	Warranty	11.1
	(Optional) Mid-Stop Limit Setting	6.9			
	Monitored Reversing Devices	6.10			

Section 1: How to use this manual

The 11 sections of this Installation Manual provide the information required to install, troubleshoot and maintain this commercial/industrial door operator.

Section 2

Provides important defining information related to safety terminology used throughout this manual, as well as safety related instructions which must be followed at all times while doing any steps/tasks/instructions detailed in this manual.

Section 3

Details pre-installation concerns/issues/decisions that are recommended to be considered and/or resolved prior to beginning any commercial door operator installation.

WARNING

Failure to correctly perform all steps in sections 4-6 can result in serious injury or death.

Sections 4-6

Provides step by step installation and set-up instructions for this commercial door operator. Each section is written such that it must be followed in a step by step order to complete a successful installation.

Sections 7-8

Details important features and troubleshooting information for typical installation and normal operations that may occur.

Sections 9-11

Provides related information on service and maintenance items, operator drawings for use in troubleshooting and service activities, along with important warranty and returned goods policy information.

Section 2: Safety Information & Instructions

⚠ WARNING

Commercial/Industrial Sectional and Rolling Steel Doors are large, heavy objects that move with the help of springs under high tension and electric motors. Since moving objects, springs under tension, and electric motors can cause injuries, your safety and the safety of others depends on you reading the information in this manual. If you have any questions or do not understand the information presented, call your nearest service representative.

To call a local Genie® Dealer, dial 800-OK-GENIE. For **Genie® Technical Service, call 800-843-4084.**

In this Manual, the words Danger, Warning, and Caution are used to stress important safety information. The word:

⚠ DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

⚠ WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

⚠ CAUTION indicates a potentially hazardous situation which, if not avoided, may result in injury or property damage.

*The word **NOTE** is used to indicate important steps to be followed or important considerations.*

POTENTIAL HAZARD	EFFECT	PREVENTION
 MOVING DOOR	⚠ WARNING Could result in Serious Injury or Death	Do Not operate unless the doorway is in sight and free of obstructions. Keep people clear of opening while door is moving. Do Not allow children to play with the door operator. Do Not change operator control to momentary contact unless an external reversing means is installed. Do Not operate a door that jams or one that has a broken spring.
 ELECTRICAL SHOCK	⚠ WARNING Could result in Serious Injury or Death	Turn off electrical power before removing operator cover. When replacing the cover, make sure wires are not pinched or near moving parts. Operator must be electrically grounded.
 HIGH SPRING TENSION	⚠ WARNING Could result in Serious Injury or Death	Do Not try to remove, repair or adjust springs or anything to which door spring parts are fastened, such as, wood block, steel bracket, cable or any other structure or like item. Repairs and adjustments must be made by a trained service representative using proper tools and instructions.

IMPORTANT READ PRIOR TO ANY DOOR OPERATION

1. Read manual and warnings carefully.
2. Keep the door in good working condition. Periodically lubricate all moving parts of door.
3. If door has a sensing edge, check operations monthly. Make any necessary repairs to keep it functional.
4. AT LEAST twice a year, manually operate door by disconnecting it from the operator. The Door should open and close freely. If it does not, the door must be taken out of service and a trained service representative must correct the condition causing the malfunction.
5. The Operator Motor is protected against overheating by an internal thermal protector. If the operator ceases to function because motor protector has tripped, a trained service technician may need to correct the condition which caused the overheating. When motor has cooled, thermal protector will automatically reset and normal operation can be resumed.
6. In case of power failure, the door can be operated manually by pulling the release cable to disconnect the operator drive system.
7. Keep instructions in a prominent location near the pushbutton.

Section 3: Critical Installation Information

Job Site Issues to Consider/Concerns

The following list of items should be considered prior to selecting an operator for a given job site.

1-Available power supply.

2-Type of door.

3-Potential operator mounting obstructions. Items to consider include, but are not limited to: side room, room above door shaft, room below door shaft, available mounting surface integrity, power supply location, and convenient chain hoist and release cable positioning.

4-Size of door for appropriate operator torque and door travel speed selection.

5-Operator mounting environment. Items to consider include operator location and dampness, dustiness and corrosiveness of the location.

6-Door activation needs/requirements. Examples include 3 button control stations, 1 button control stations, radio controls, pull cords, loop detectors, photoelectric controls, key switches, etc. See "Entrapment Protection" section below.

7-Interlock switches are required under certain conditions for doors with pass doors and door locks. See page 5.5.

8-Accessory equipment. Examples are reversing edges and/or photocell beams (required for doors set to operate as momentary contact), auxiliary control relays, warning lights, etc.

⚠ ENTRAPMENT PROTECTION

The installation of a fail safe external reversing device (such as a monitored reversing edge or photocell system, etc.) is required on all momentary contact electronically operated commercial doors. If such a reversing device is not installed, the operator will revert to a constant contact control switch for operation (Closing only).

The Reversing Devices currently UL Approved with are:

- 1) MillerEdge ME, MT and series monitored edge sensors used in combination with Timer-Close Module P/N OPABTCX.S or OPAKMEIX.S INTERFACE MODULE.
- 2) Residential Safe-T-Beam® Monitored Photocells from The Genie® Company, model OSTB-BX (P/N 38176R).
- 2) Series II Commercial Safe-T-Beam®, Monitored Photocells P/N OPAKPE.S.
- 3) Series II Commercial Safe-T-Beam®, Monitored Photocells P/N OPAKPEN4GX.S.

⚠ WARNING: DO NOT apply line voltage until instructed to do so.

⚠ CAUTION:

Check working condition of door before installing the operator. Door must be free from sticking and binding. If equipped, deactivate any door locking device(s). Door repairs and adjustments, including cables and spring assemblies MUST be made by a trained service representative using proper tools and instructions.

Section 3: Critical Installation Information

ENTRAPMENT PROTECTION

The **GCL-GT™** can be used with the following UL Listed entrapment devices in compliance with UL325 requirements active starting August 29, 2010.

UNTIL ONE OF THESE MONITORED EXTERNAL ENTRAPMENT DEVICES IS INSTALLED, THE OPERATOR WILL NOT ALLOW MOMENTARY CONTACT OPERATION IN THE CLOSE DIRECTION.

LISTED DEVICES	ALLOWABLE DOOR WIDTH
MillerEdge ME, MT and CPT series monitored edge sensors used in combination with Timer-Close Module or OPAKMEIGX.S Interface Module.	ANY WIDTH
Residential Safe-T-Beam® Monitored Photocells model OSTB-BX P/N 38176R.	30 FEET
Commercial Monitored Photoeye Kit P/N OPAKPE.S	30 FEET
Commercial NEMA4 Monitored Photocells P/N OPAKPEN4GX.S.	35 FEET

Rolling Steel Door Chart (sq. ft.)

Model	HP	UL Listed	STEEL, NON-INSULATED						STEEL, INSULATED			COUNTER DOOR		GRILLES		FIRESTAR 2" SLAT		FIRESTAR 3" SLAT				FIRESTAR 3" SLAT INSULATED	SHEET DOOR	
			16GA.	18GA.	20GA.	22GA.	24GA.	26GA.	18GA.	20GA.	22GA.	ALUM.	STL/SST	ALUM.	STL/SST	20GA.	22GA.	16GA.	18GA.	20GA.	22GA.	20GA.	22GA.	26GA.
GCL-GH	1/2	YES	250	277	277	333	360	360	194	194	222	126	126	360	280	210	270	128	144	166	220	120	128	256
GCL-GH	3/4	YES	283	350	350	442	494	N/A	232	232	283	126	126	490	350	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
GCL-GH	1	YES	318	420	420	548	636	N/A	244	244	303	N/A	N/A	580	380	320	355	176	188	246	272	160	180	N/A
GCL-GH	3	YES	962	1035	1152	1152	1152	N/A	728	728	986	N/A	N/A	982	982	576	576	342	390	576	576	300	324	N/A

Note: Total door weight and not square footage is the critical factor in selecting the proper operator. These Sq.Ft. measurements are based on square doors, e.g. 16' x 16'.

Unbalanced Fire Shutters have a maximum square footage of 52 for 22GA. steel and 42 for 20GA. steel.

Sectional Door Chart (sq. ft.)

Model	HP	UL Listed	Commercial Steel Insulated & Non-Insulated																	Thermospa				Thermomark		Aluminum	
			Door Series ->		216	216 ins.	220	220 ins.	2415	2415 ins.	2411	2411 ins.	125	150	200	200-20	5150	5200	451	452							
			Mounting Type	Max. Door Weight (Lbs)	16GA. Flush Steel	16GA. Flush Steel Insulated	20GA. Ribbed Steel	20GA. Ribbed Steel Insulated	24GA. Ribbed Steel	24GA. Ribbed Steel Insulated	Nominal 24GA. Ribbed Steel	Nominal 24GA. Ribbed Steel Insulated	PU/FIP Insulated	PU/FIP Insulated 1.38"	PU/FIP Insulated 2"	PU/FIP Insulated 2" 20GA. Exterior	PU/FIP Insulated Raised Panel 1.38"	PU/FIP Insulated Raised Panel 2"	1/8" Glass 1.38"	1/4" or 1/2" Glass 1.38"							
GCL-GH	1/2	Yes	TSC	1310	300	256	410	280	520	400	320	320	256	430	430	350	450	430	400	320							
GCL-GH	3/4	Yes	TSC	1450	340	256	450	320	540	410	320	320	256	450	450	400	480	460	400	350							
GCL-GH	1	Yes	TSC	1650	390	290	510	380	580	410	320	320	256	480	480	420	510	490	400	400							
GCL-GH	3	Yes	SC	3696	700	500	700	560	770	600	320	320	256	480	900	680	530	680	400	400							

T=Trolley S=Jackshaft, SideMount C=Jackshaft, CenterMount

Note: Total door weight, and not the square footage, is the critical factor in selecting the proper operator.

Square footage measurements are based on "square doors." (Example=16' x 16')

NOTE: Doors that require special windloading and wide doors, normally require increased strutting (reinforcement). Strutting doors can significantly increase door weight beyond weight shown. Consult Customer Service for the impact of wind load and strutting on square foot limits.

NOTE: "PU-FIP" stands for "polyurethane, foamed-in-place." If no notation is present, insulation is "polystyrene, laid-in-place."

Section 3: Critical Installation Information

IMPORTANT INSTALLATION INSTRUCTIONS

WARNING -

To reduce the risk of severe injury or death:

- 1) READ AND FOLLOW ALL INSTALLATION INSTRUCTIONS.
- 2) Install only on a properly operating and balanced door. A door that is operating improperly could cause severe injury. Have qualified service personnel make repairs to cables, spring assemblies and other hardware before installing the operator.
- 3) Remove all pull ropes and remove, or make inoperative, all locks (unless mechanically and/or electronically interlocked to the power unit) that are connected to the door before installing the operator.
- 4) Install the door operator at least 8 feet above the floor if the operator has exposed moving parts.
- 5) Do not connect the door operator to the power source until instructed to do so.
- 6) Locate the control station: (a) within sight of the door, (b) a minimum of 5 feet above the floor so that small children cannot reach it, and (c) away from all moving parts of the door.
- 7) Install the Entrapment Warning Placard next to the control station and in a prominent location.
- 8) For products having a manual release, instruct the end user on the operation of the manual release.

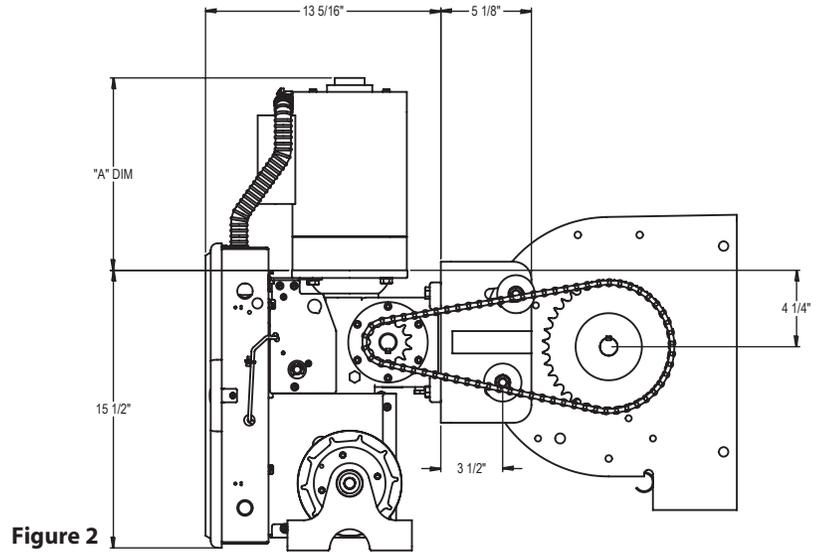
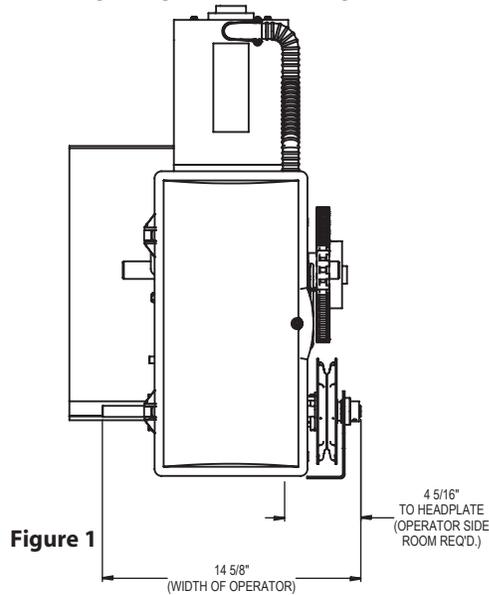
Section 4: Installation

Rolling Steel Front of Hood

The Rolling Steel Door Operator can be assembled for **right-hand** or **left-hand** mounting **Front of Hood**.

Each model can also be wall mounted (next pages).

- 1) Mounting hardware and instruction will be supplied based on door specifications.
(Typical mounting arrangements shown in figures 1 and 2.)



Rolling Steel/Sectional Wall Mount/Side Mount

The Hoist unit can be wall mounted when required. **Fig. 5, 6 & 7.**

- 1) Attach optional wall mount bracket to operator (optional) using the 4 mounting bolts and nuts supplied. Fully tighten. Position the operator with the bracket as shown.
- 2) Attach 12 tooth sprocket to operator output shaft.
- 3) Align keyways and insert key into sprocket and door shaft keyway. Do not tighten set screw at this time.
- 4) Attach door sprocket to door shaft. Do not tighten at this time.
- 5) Assemble chain using chain master link.
- 6) Position operator near door shaft with sprockets aligned.
- 7) Place assembled chain over door and operator sprockets.
- 8) Lift or lower the operator as needed to tension drive chain.
- 9) Secure operator to wall.
- 10) Check vertical alignment of the drive chain/sprockets and tighten sprocket set screws.
- 11) Lock the operator in place using the LOCK DOWN HOLES indicated in **Fig. 5**. These **MUST BE USED** to prevent any shifting of the operator due to the torque applied during operation. (These are in addition to the slotted mounting holes.)

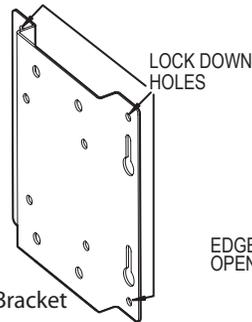


Figure 5
Optional Bracket

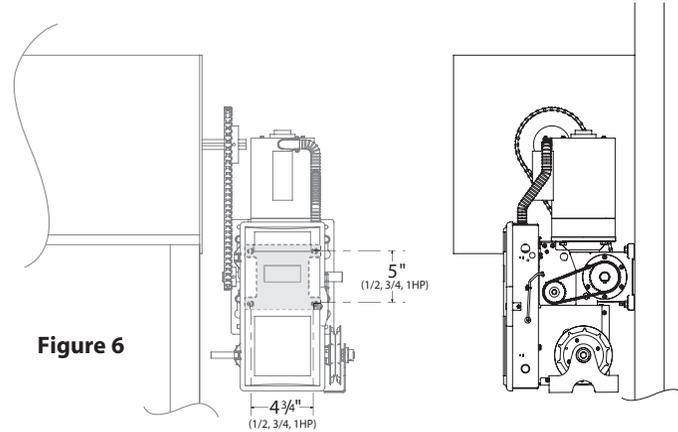


Figure 6

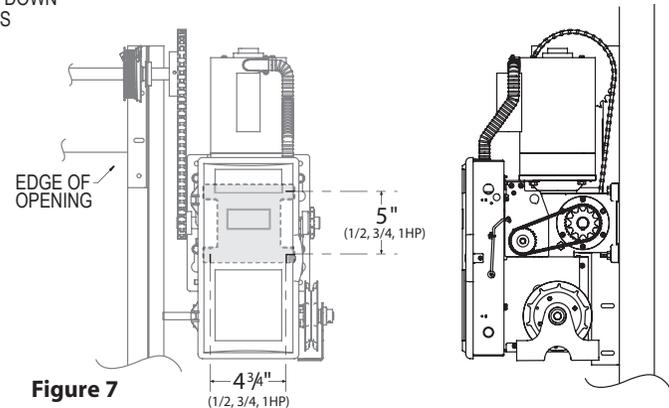


Figure 7

Chain Couple

For Hollow Counterbalance Door Shaft:

- 1) Use non-threaded hole in door shaft sprocket as a guide and drill a 3/8" diameter hole through one side of the door shaft. **Fig. 4A.**
- 2) Insert clevis pin through sprocket and shaft to hold sprocket in position.
- 3) Drill through opposite side of shaft to obtain proper hole alignment. **Fig. 4B.**
- 4) Insert clevis pin through both holes and secure with cotter pin. **Fig. 4C.**

For Solid Counterbalance Door Shaft:

- 1) Insert key into door shaft keyway.
- 2) Slide sprocket into place and secure with set screws.

To Complete the Installation:

If needed, realign operator sprocket with door sprocket. If you have excessive door shaft movement, an optional chain tension plate is available, pg 4.4.

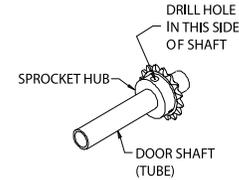


Figure 4A

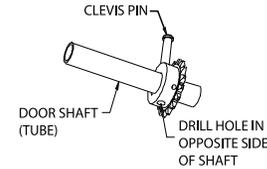


Figure 4B

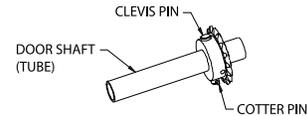


Figure 4C

Chain Couple Tension Bracket

Bracket is available as an optional kit, P/N 111005.0001.S

Installation of optional chain spreader bracket: Fig 5A & 5B.

- 1) Place sprocket, upper plate and bearing assembly on door shaft as shown.
- 2) Place lower plate, bearing assembly and sprocket on operator shaft as shown.
- 3) Install door and operator sprockets and chain assembly as described on page 4.2.
- 4) Install bolts and nuts through plates.
- 5) Tighten and align chain and plate and secure operator to wall.
- 6) Tighten spreader bracket bolts.

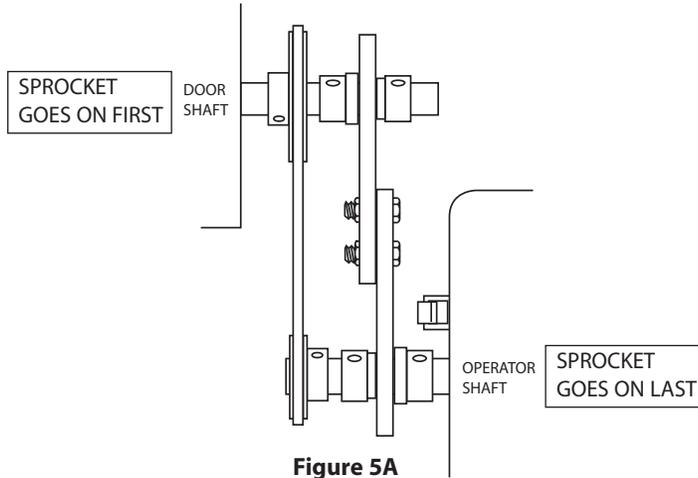
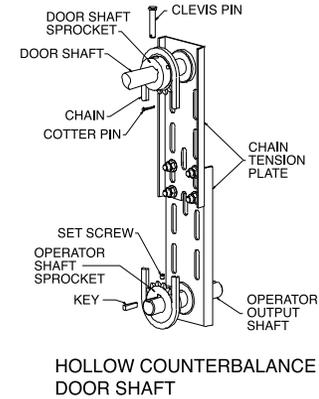


Figure 5A



HOLLOW COUNTERBALANCE
DOOR SHAFT

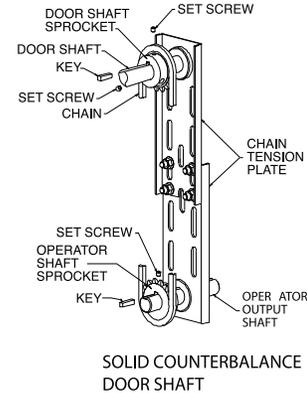


Figure 5B

Unpacking and Configuring Release Cord: Fig. 9

The cord comes shipped connected to the Release Lever and looped around the end of the hoist shaft opposite the handwheel, with the bulk of the cord taped to the handwheel side of the brake enclosure (SIDE A).

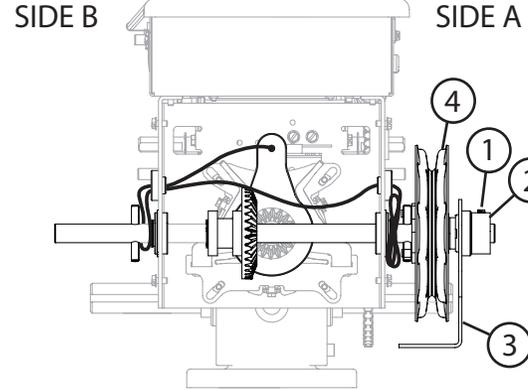
- 1) Untape the bulk of the cord from the side panel of brake enclosure. Straighten cord, ensuring there are no kinks or knots.
- 2) Determine which side you want the cord to be on.
 - **For use on SIDE A**, unloop cord from the SIDE B end of hoist shaft and pull it out through SIDE A hole.
 - **For use on SIDE B**, pull cord out through SIDE B hole.

Shifting Manual Handwheel SIDE A to SIDE B: Fig. 9

The release mechanism is factory installed and is designed so that it can be right or left-hand mount. To switch the handwheel:

- 1) Loosen the set screws (1) and remove set collar (2).
- 2) Slide the chain guard (3) and handwheel (4) off of hoist shaft.
- 3) Slide all onto opposite side in order shown and tighten set screws.

Figure 9



Handwheel, Chain and Keeper

- 1) Route the hand chain through the chain guide, around the pocket wheel and back through the chain guide. **Fig. 10.**
- 2) Connect the hand chain ends together as shown in **Fig. 11.** by twisting open the last link on one end of the chain, and slipping the last link on the opposite end onto the open link.
- 3) Twist open link closed again.
- 4) Mount chain keeper to wall in line with chain approximately 4 feet from floor.
- 5) Loop chain around keeper as shown. **Fig. 12** Optional Padlock not provided.

NOTE: To insure smooth operation, make sure there is no twist in the hand chain before connecting the link ends together.

Figure 10

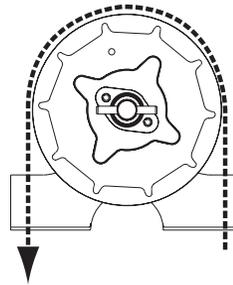


Figure 11

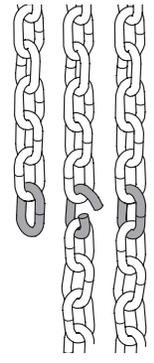
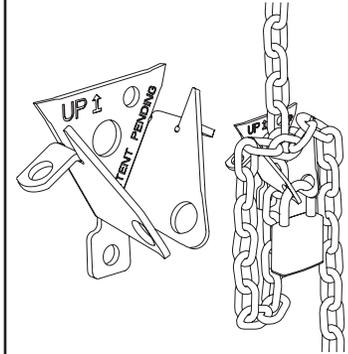


Figure 12



Adjusting the Clutch (Optional)

NOTE: The clutch is intended to provide protection for the door, operator and associated equipment. It is not intended for entrapment protection.

The clutch does not require any disassembly to adjust.

- 1) All adjustments should be made in very small increments (e.g. turning adjustment bolts 1/4 turn per increment).
- 2) When making adjustments, be sure to turn all 3 adjustment bolts an equal amount. **Fig 13.**
 - To increase tension, turn adjustment bolts clockwise.
 - To decrease tension, turn adjustment bolts counter-clockwise.
- 3) Clutch needs to be adjusted to a tension just above what is required to open and close door without clutch slippage.

NOTE: Periodically check the system for proper clutch action. If clutch starts to slip after working properly for some time, check manual operation of door before adjusting clutch. Door may not be operating freely or counter-balance spring may need adjusting. Repairs and adjustments must be performed by a trained service representative using proper tools and instructions.

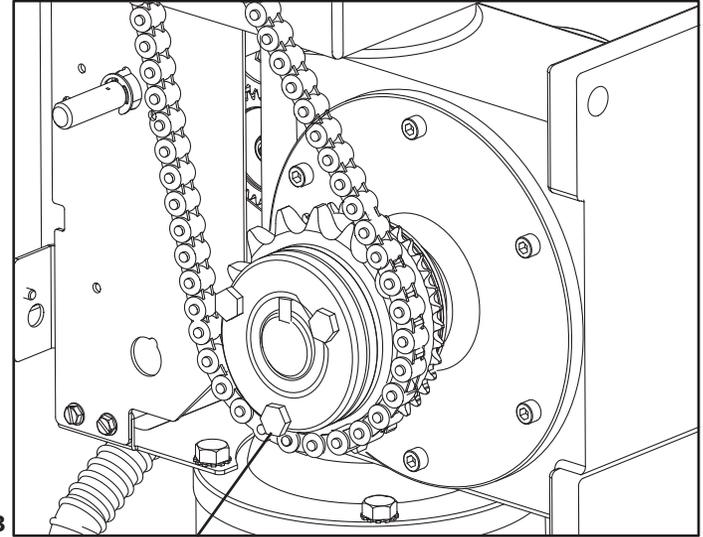


Figure 13

ADJUSTMENT
BOLTS

Section 5: Wiring

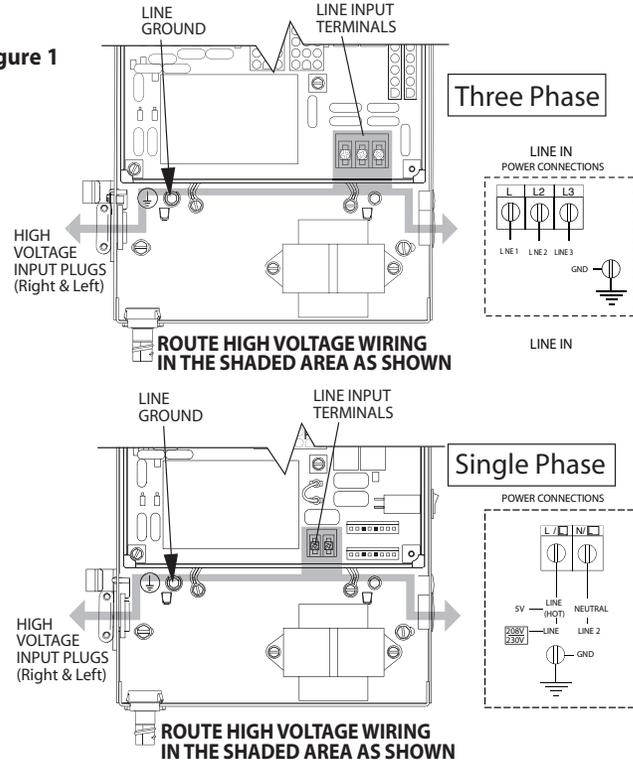
Line Voltage Wiring Fig. 1

⚠WARNING

- DO NOT apply power to operator until instructed to do so.
- It is strongly recommended, and may be required by law in some areas, that line voltage wiring be performed by a qualified electrician.
- Be sure that electrical power has been disconnected from the input power wires being connected to the operator prior to handling these wires. An appropriate lock-out / tag-out procedure is recommended.
- Line voltage wiring must meet all local building codes.
- Make sure operator voltage, phase and frequency nameplate ratings are identical to the job site line voltage ratings.
- Input power wiring must be properly sized for the operators amperage rating located on the nameplate.
- To reduce the risk of electric shock, make sure the chassis of this unit is properly grounded.

- 1) Remove LINE VOLTAGE INPUT PLUG and install proper fittings and 1/2" conduit.
- 2) Route proper LINE VOLTAGE wires into operator.
- 3) Locate LINE INPUT terminals on circuit board. Using correct connectors, attach wires to LINE INPUTS, and GROUND terminal.
 - Keep low voltage and line voltage wires separate.
 - Route all line voltage wires as shown.
 - Plug all unused conduit holes.

Figure 1



Low Voltage Control Wiring (general) Fig. 2

- 1) Connect all LOW VOLTAGE control circuit wires to this side of unit using 1/2" conduit or flexible convoluted tubing.
 - Keep low voltage and line voltage wires separate.
 - Route all low voltage control wiring as shown. This includes all control circuit wires such as wall controls, timers and single button input devices as well as radio control and safety circuit wiring. See Figs 2 through 10 in this section.
 - Plug all unused conduit holes.

NOTE: For a detailed description of control wire terminals see Appendix B.

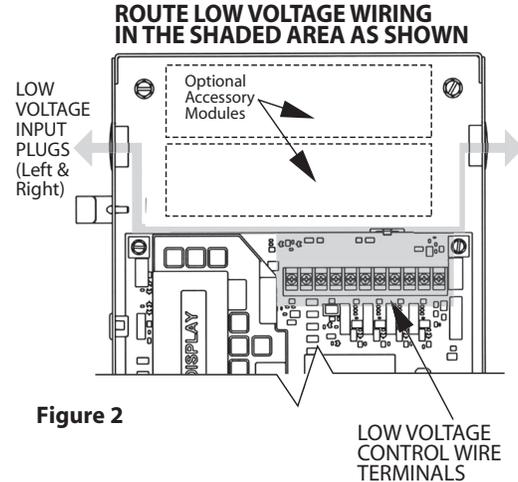
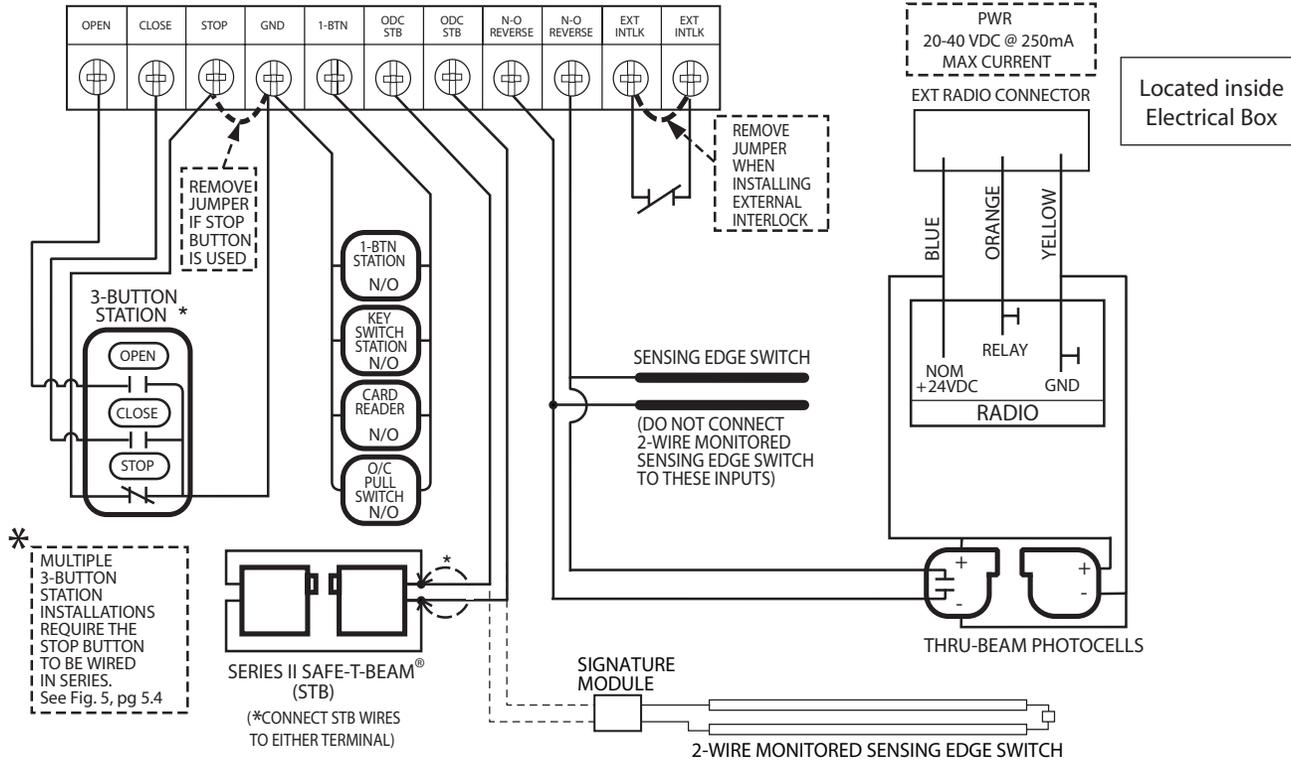


Figure 2

External Wire Diagram

See Appendix B for detailed description of terminals.



Wall Control

WARNING:

- Wall Control(s) must be located so that the door is within sight of the user.
- Attach the Warning placard adjacent to the Wall Control. **Fig. 3A.**

WARNING:

If momentary contact control is to be used, an external reversing device such as a photocell system or sensing edge switch must be used. See pages 5.6-5.7 for installation of entrapment protection devices.

- 1) For a single 3 - button installation, make connections as shown in **Fig. 3.**
- 2) For single button accessory controls, make connections as shown in **Fig. 4.**
- 3) For a multiple 3 - button installations, make connections as shown in **Fig. 5.**

NOTE: If an External STOP button is NOT being installed, a jumper wire must be installed between the "STOP" AND "GND" terminals as shown.

NOTE: Long Distance Relay Kit wiring is not required for long distance control runs and should not be used.

Figure 3

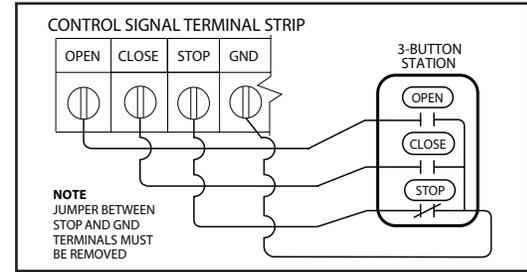


Figure 3A



Entrapment
Warning
Placard

Figure 4

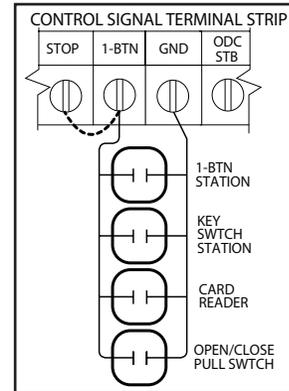
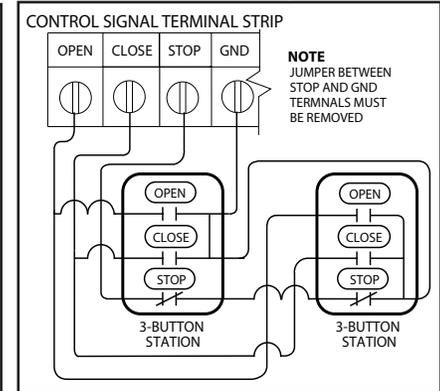
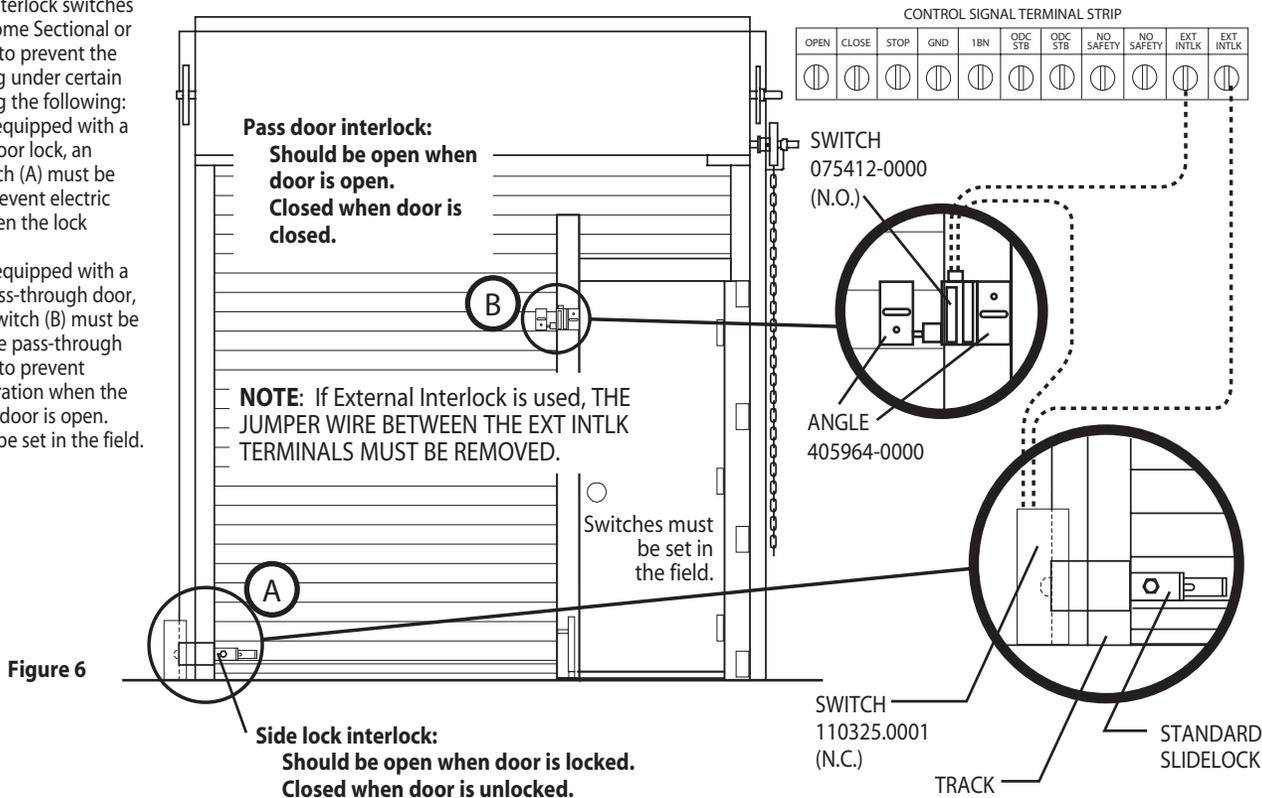


Figure 5



Interlock Switches

- 1) Optional external interlock switches are required with some Sectional or Rolling Steel Doors to prevent the door from operating under certain conditions including the following:
 - If the door is equipped with a functioning door lock, an interlock switch (A) must be installed to prevent electric operation when the lock is engaged.
 - If the door is equipped with a pedestrian pass-through door, an interlock switch (B) must be installed at the pass-through door in order to prevent electrical operation when the pass-through door is open.
- 2) The Switches must be set in the field.



Photocell Wiring

Series II Safe-T-Beam® Monitored Photocells

- 1) Monitored SERIES II (STB) photocells (P/N OPAKPE.S) can be installed as shown in **Fig. 7**. Wiring to these photocells can be connected to either terminal (they are not polarity sensitive).
(Troubleshooting in Section 8)

NOTE: Installer must enable ODC STB in calibration mode. See page 6.9.

NOTE: A monitored sensing device must be installed or the unit will be Constant Contact Close.

⚠ WARNING: Actuating operator using constant contact on the CLOSE button will override external reversing devices, including photocells.

- 2) **To Mount Photocells:** (Kit includes detailed Instructions).
 - Determine location for mounting. They do not need to be directly adjacent to the door but must be somewhere along the wall where there will be an unobstructed line between them. **Fig 9**.
 - They must extend out away from the wall sufficiently that no door hardware breaks the plane of the photo-beam.

⚠ WARNING: Photocell systems provide entrapment protection when mounted near the doorway in such a way that the lower portion of an individual's leg will break the photocell beam during normal walking conditions.

Commercial Non-Monitored Photocells

- 1) Nominal 24 Volt DC Commercial photocells with normally open contacts can be connected as shown in **Fig. 8**.

NOTE: Blue wire supplies 20 – 40VDC. Photocells used must be compatible with this voltage range.

NOTE: If no voltage is present at Blue wire, check fuse F-1 on Control board.

CONNECT WIRES TO EITHER TERMINAL.
(NOT POLARITY SENSITIVE)

Figure 7

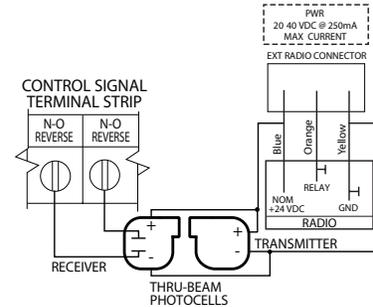
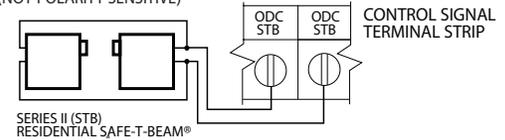


Figure 8

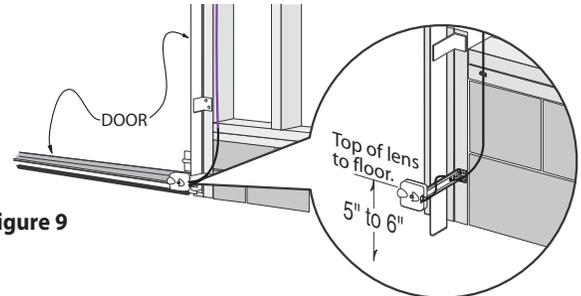


Figure 9

Sensing Edge Switch Installation

Figure 11 shows an example of a typical sensing edge installation. Left hand side is shown but right hand is a mirror image of this.

- 1A) If wiring from sensing edge switch to operator is coiled cord or 2 wire jacketed cord:
 - Install junction box 12" above the center of the door opening on same side as sensing switch.
 - Secure one end of cord to junction box using a cable clamp.
- 1B) If connection is to be made through a take up reel cord:
 - Install on same side as sensing edge switch and above door opening and slightly to the side.
 - Install junction box adjacent to take up reel and route the stationary cord from the reel to the box and secure with a cable clamp.

NOTE: Do not use a take-up-reel on a monitored edge. They have slip connections in them that momentarily break contact which causes false reversals.

- 2) Secure other end of cord (straight, coiled or reel) to sensing edge switch enclosure using a cable clamp.
- 3) Connect wires of cord to sensing edge switch using wire nuts or other suitable wire connectors.
- 4) Run a straight 2 wire cord from the junction box (Step 1) to the operator electrical box.
 - Secure using cable clamp on each end.
- 5) Join wires in cord from operator to wires in cord from switch using wire nuts or other suitable wire connectors.
- 6A) **Monitored** sensing or reversing edge connects to optional Timer-Close Module terminals shown in **Fig. 10A**.
- 6B) **Monitored** sensing edge connects to main circuit board ODC STB terminals using the optional OPAKMEIGX.S as shown in **Fig. 10B**.
- 7) Operate the door to make certain cord is free to travel and does not become snared during door opening or closing.
 - Check sensing edge switch for proper operation.

⚠ WARNING: Actuating the operator using constant contact on the CLOSE button will override external reversing devices, including sensing edges or reversing edges.

Figure 10A

NOTE Monitored 2-wire sensing or reversing edge can only be used in combination with a Timer-Close Module.

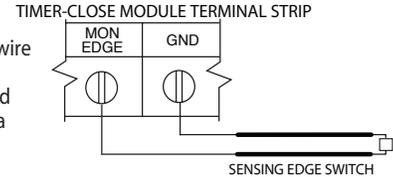


Figure 10B

NOTE: Monitored sensing edge connects to main circuit board ODC STB terminals using optional OPAKMEIGX.S INTERFACE MODULE.

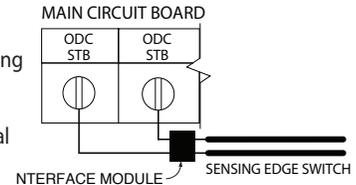
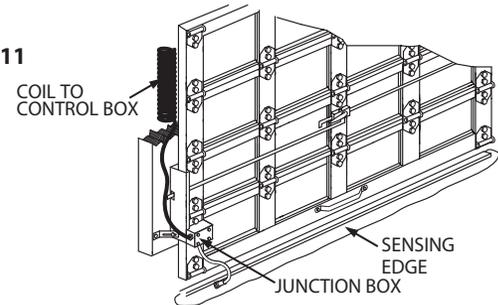


Figure 11

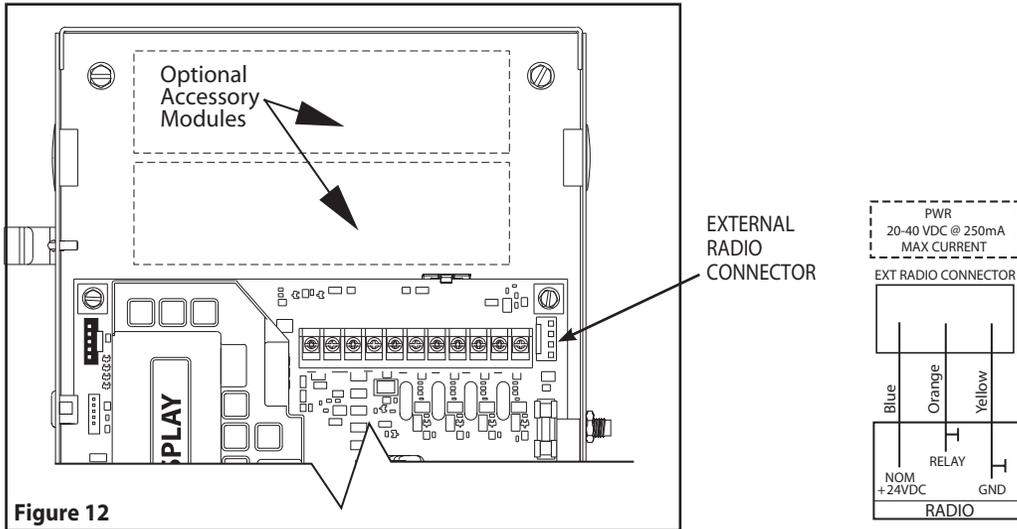


External Radio Installation

Although these operators are equipped with an internal radio, they also provide a universal connection for an external radio.

To Add the External Radio

- 1) Plug the pigtail with the 3 wires attached (provided) onto the plug connector marked "EXT RAD." **Fig. 12.**
- 2) Make wiring connections to the wires per the diagram below.

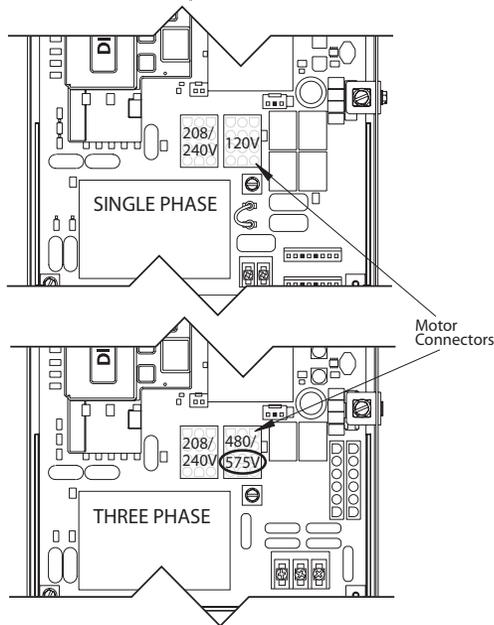


⚠ WARNING:

Verify Line Voltage before making any connections to assure that motor harness is connected to proper motor connector on circuit board.

- 1) Plug motor harness into proper motor connector on circuit board in electric box. **Fig. 13.**
- 2) Apply primary power.

Figure 13



IMPORTANT SAFETY INSTRUCTIONS

WARNING -

To reduce the risk of severe injury or death:

- 1) READ AND FOLLOW ALL INSTRUCTIONS.
- 2) Never let children operate or play with door controls. Keep the remote control (where provided) away from children.
- 3) Personnel should keep away from a door in motion and keep the moving door in sight until it is completely closed or opened. **NO ONE SHOULD CROSS THE PATH OF A MOVING DOOR.**
- 4) Test the door's safety features at least once a month. After adjusting either the force or the limit of travel, retest the door operator's safety features.
- 5) For products having a manual release, if possible, use the manual release only when the door is closed. Use caution when operating the release while the door is open. Weak or broken springs may cause the door to fall rapidly, causing severe injury or death.
- 6) **KEEP DOOR PROPERLY OPERATING AND BALANCED.** See Door Manufacturer's Owner's Manual. An improperly operating or improperly balanced door could cause severe injury or death. Have only trained door systems technicians make repairs to cables, spring assemblies, other hardware and any wooden blocks or like items to which they may be attached.
- 7) **SAVE THESE INSTRUCTIONS.**

⚠ DANGER: After power is supplied to the operator, **Do Not** make contact with components inside the control panel except for the Keypad Keys. **Fig. 1.**

Section 6: Operator Setup Procedure

Control Panel

These operators include a full function control panel including a liquid crystal display (LCD), calibration keys and Open, Close and Stop keys for on board operator control. See **Fig. 1**. The open, close and stop keys function as a 3-button wall control. The Display will show current operator conditions and calibration information. Due to limited character space, some displays will be abbreviated. See Appendix C (pgs. 10.9-10.11) for full display descriptions.

Operators also include a non-volatile memory. The unit will remember all calibration settings plus error code and run code logs, if power is removed from unit.

⚠ DANGER: After power is supplied to the operator, **Do Not** make contact with components inside the control panel except for the Keypad Keys. **Fig. 1.**

TURN ON POWER TO OPERATOR

Control Operating Modes

Operator control boards operate in two modes: Run Mode and Calibration Mode. The control board should normally operate in the Run Mode. The operator is calibrated in Calibration Mode.

With the operator standing idle:

PRESS CAL/RUN TO TOGGLE BETWEEN OPERATING MODES.

- The first display in calibration mode is "set close dir."
- The display in run mode will be one of the condition codes listed in Appendix D.

⚠ WARNING: DO NOT calibrate operator or operate door unless doorway is in sight and free of obstructions. Door will move during setup. Keep people clear of opening while door is moving.

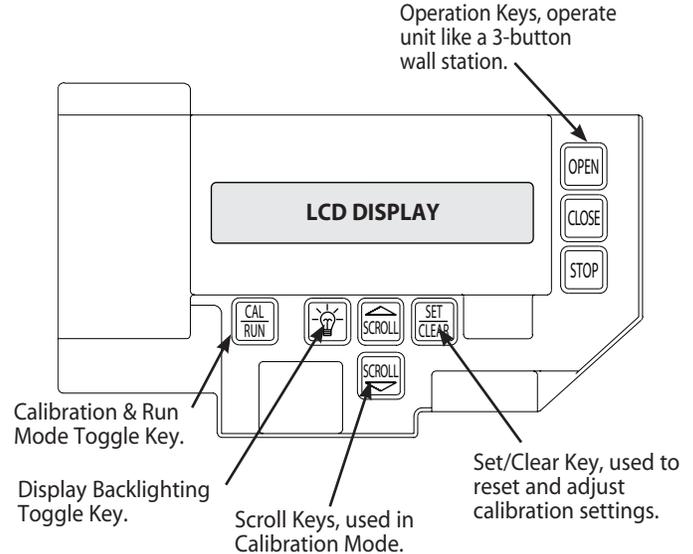


Figure 1

Setting Constant Contact

These operators are shipped from the factory with both open and close operating modes set to constant contact – stop (C – STP) If your unit is set to Momentary Contact (MOM) Open and/or CLOSE, reset the operating modes by taking the following steps:

- 1) Press CAL/RUN to enter calibration mode. **Fig. 2.**
- 2) Press SET/CLEAR until display reads "OPEN MODE > C-STP." **Fig. 3.**
- 3) Press SCROLL (DN) until display reads "CLOSE MODE." **Fig. 4.**
- 4) Press SET/CLEAR until display reads "CLOSE MODE > C-STP." **Fig. 5.**

⚠WARNING: If a monitored external reversing device is not used, then the operator will run Constant Contact Close. Verify close mode is set to "C-STP" and NOT "C-REV" or "MOM" before continuing.

- 5) Press CAL/RUN to return to run mode.

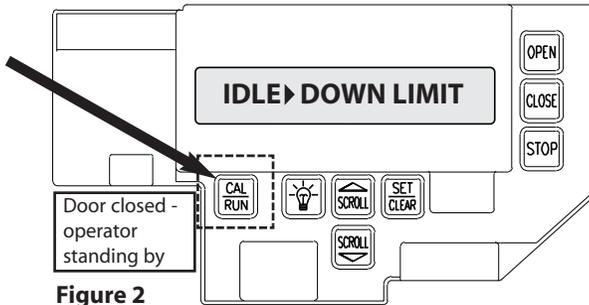


Figure 2

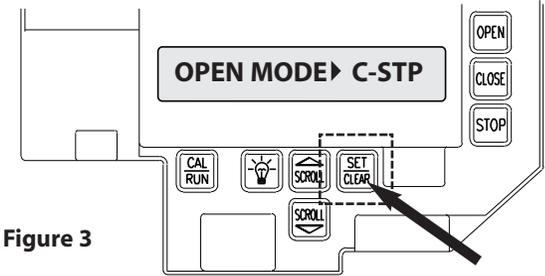


Figure 3

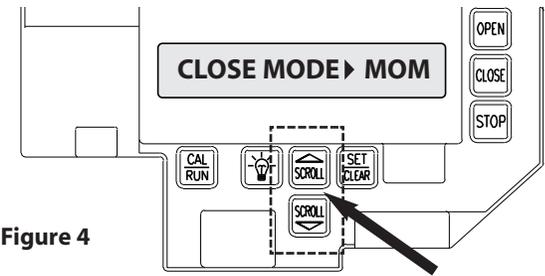


Figure 4

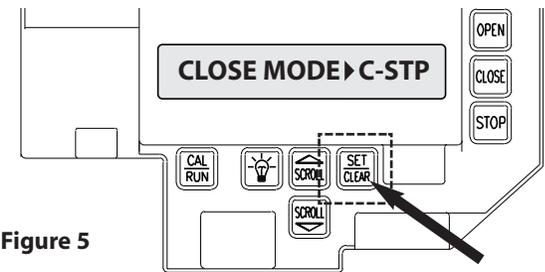


Figure 5

Setting Braking Rate

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press Scroll until display reads "BRAKING RATE >#." where # is the deceleration rate, ranging from 0 to 9.
0 = MAX braking, 9 = MIN braking. **Figure 6.**
- 3) Press SET/CLEAR  key to toggle between 0 and 9—one digit at a time.
- 4) Pick a value and operate the door. Adjust as necessary.
- 5) Press a SCROLL  key to shift to a new function and lock in the setting.
- 6) Press CAL/RUN  to return to run mode.

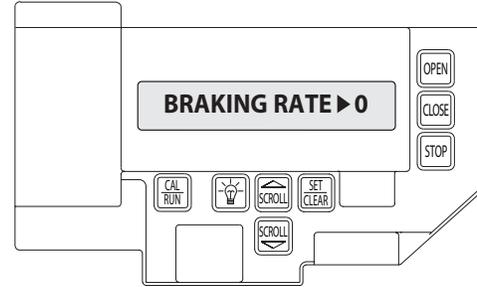


Figure 6

Setting Travel Limits

UP and/or DOWN

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "UP LIMIT>CLR " or "DOWN LIMIT>CLR " **Figure 7.**
- 3) Jog the door using the OPEN  or CLOSE  key until you reach the desired height.
- 4) Press SET/CLEAR  key to switch display to "UP LIMIT>SET " or "DOWN LIMIT>SET ." **Figure 8.**
- 5) Press a SCROLL  key to shift to a new function and lock in the limit setting.
- 6) Press CAL/RUN  to return to run mode.

Resetting Travel Limits

UP and/or DOWN

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "UP LIMIT>SET " or "DOWN LIMIT>SET." **Figure 8.**
- 3) Press SET/CLEAR  to switch display to "UP LIMIT>CLR" or "DOWN LIMIT>CLR"
- 4) Jog the door using the OPEN  or CLOSE  key until you reach the desired height.
- 5) Press SET/CLEAR  to switch display to "UP LIMIT>SET" or "DOWN LIMIT>SET"
- 6) Press CAL/RUN  to return to run mode.

NOTE: The recommended setpoint for the DOWN Travel Limit is normally at approximately 2 inches off the floor. This final distance will be covered by the Limit Overrun Function to establish a more accurate seal.

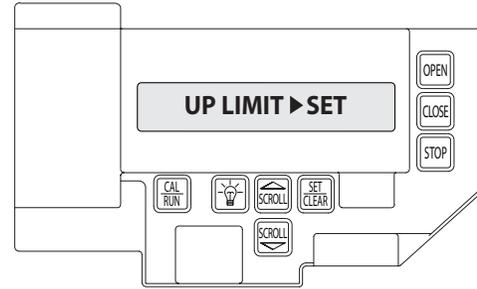


Figure 7

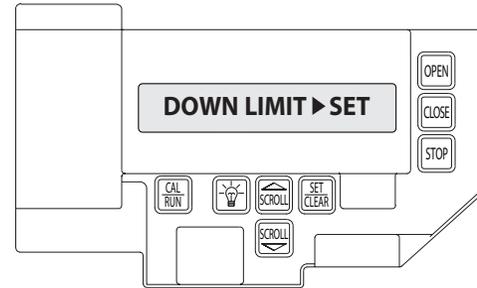


Figure 8

Setting Limit Overrun

⚠ WARNING: The Limit Overrun function will override external reversing devices, including photocells and sensing edges or reversing edges. Therefore, any externally connected devices will be disabled during that portion of the door travel controlled by the Limit Overrun function. The Down Limit Overrun function should be used to close the door no more than the final 2".

- A)** The Limit Overrun setting is a matter of trial and error. The goal is to adjust the Limit Overrun until an appropriate seal is obtained between the bottom edge of the door and the floor.
- B)** The Limit Overrun setting can be varied between 0 and 9. 0 - disables the Limit Overrun so that the door stops at the down limit switch setting. 9 - causes the greatest amount of door travel beyond the limit switch setting. Door should close gently with light tension on door cables, or minimal stacking on rolling steel slats.
- 1) Press CAL-RUN to enter calibration mode
 - 2) Press scroll (▼) until the display reads "LIMIT OVERRUN >(0-9)." **Fig. 8.**
 - 3) Press SET/CLEAR until the display reads the desired value.
 - 4) Press the OPEN key to open the door a few feet, then release
 - 5) Press the CLOSE key to close the door and hold until the operator stops.
 - 6) Check the door seal and repeat steps 3-5 until the appropriate seal is obtained between the door and the floor.

⚠ CAUTION: If proper seal cannot be obtained at a setting of 9, Reset the Limit Overrun back to 0 and reset the Down Limit position as described on pg. 6.3. Then adjust the Limit Overrun as instructed above.

- 7) Press CAL-RUN to return to run mode.

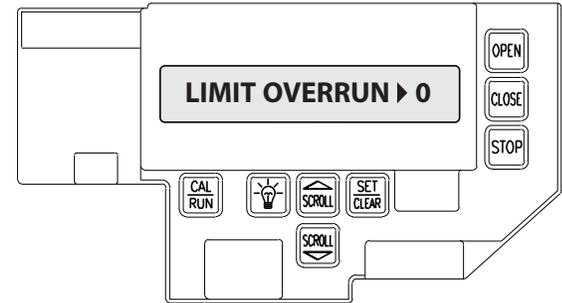


Figure 8

Setting Open and Close Modes (Constant vs Momentary Contact)

OPEN

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "OPEN MODE>MOM" or "OPEN MODE>C-STP." **Figure 10.**
 - MOM=momentary contact, meaning you **press and release** the OPEN  or CLOSE  key and **the door will continue to move** until it reaches its travel limit. (See NOTE)
 - C-STP=constant contact-stop, meaning **if you release the key** prior to the door reaching its travel limit, **the door will stop.**
- 3) Press SET/CLEAR  key to toggle between "OPEN MODE>C-STP" or "OPEN MODE>MOM" on the display.
- 4) Press a SCROLL  key to shift to a new function and lock in the setting.
- 5) Press CAL/RUN  to return to run mode.

CLOSE

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "CLOSE MODE>MOM," "CLOSE MODE>C-STP" or "CLOSE MODE>C-REV." **Figure 10.**
 - MOM=momentary contact, meaning you **press and release** the OPEN  or CLOSE  key and **the door will continue to move** until it reaches its travel limit. (See NOTE)
 - C-STP=constant contact-stop, meaning **if you release the key** prior to the door reaching its travel limit, **the door will stop.**
 - C-REV=constant contact-reverse, meaning **if you release the key** prior to the door reaching its travel limit, **the door will reverse direction.** (See NOTE)
- 3) Press SET/CLEAR  key to toggle between "CLOSE MODE>C-STP" or "CLOSE MODE>C-REV" or "CLOSE MODE>MOM" on the display.
- 4) Press a SCROLL  key to shift to a new function and lock in the setting.
- 5) Press CAL/RUN  to return to run mode.

NOTE: Momentary contact (**MOM**) or Constant Reverse (**C-REV**) may not be used unless both the OPEN and CLOSE Limits have been set.

In situations where an external reversing device is either not installed or not operating properly, Constant Contact (**C-STP**) **MUST BE USED.**

⚠ WARNING: Before momentary contact control can be used, an external reversing device such as a photocell system or sensing edge switch must be used. See pages 5.6-5.7 for installation of entrapment protection devices.

NOTE: During adjustment of a Travel Limit, the Open and Close Modes will automatically fail-safe to Constant Contact until the Limit has been set or reset. At that time the Open and Close Modes will revert to their previous setting.

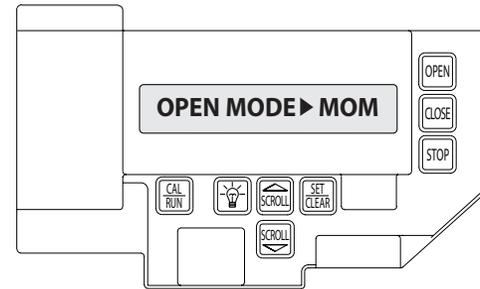


Figure 10

(Optional) Transmitter Programming

Adding a Transmitter

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  (up or down) until display reads "LEARN NEW XMTR?"
Figure 11.
 - This question along with the instruction "HIT SET FOR YES" will continuously pan across the display window. (Pressing SCROLL or RUN/CAL will cancel the operation.)
- 3) Press SET .
- 4) Press Transmitter button two times.
 - The display will read "XMTR ____ LEARNED." Where it assigns a random number between 1 and 50 to the transmitter. That transmitter is entered and ready to operate the door. (Label/mark the transmitter.)
- 5) Press SCROLL  (up or down) to move on to another menu item, or CAL/RUN  to exit the CAL mode.

Removing Individual Transmitter

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  (up or down) until display reads "REMOVE XMTR?"
Figure 12.
 - This question along with the instruction "HIT SET FOR YES" will continuously pan across the display window. (Pressing SCROLL or CAL/RUN will cancel the operation.)
- 3) Press SET .
- 4) Press SET .
- 5) Press SCROLL  (up or down) to move on to another menu item, or CAL/RUN  to exit the CAL mode.



Figure 11



Figure 12



Figure 13

Removing All Transmitters

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  (up or down) until display reads "REMOVE ALL XMTRS?"
Figure 13.
 - This question along with the instruction "HIT SET FOR YES" will continuously pan across the display window. (Pressing SCROLL or CAL/RUN will cancel the operation.)
- 3) Press the SET  key.
 - The display will read "ARE YOU SURE."
- 4) Press the SET  key.
 - All transmitters are removed.
- 5) Press SCROLL  (up or down) to move on to another menu item, or CAL/RUN  to exit the cal mode.

Optional Mid-Stop Limit Setting

The GH™ Operator includes a programmable Mid-Stop. This feature allows the operator to stop at a user selectable point when opening. It is used when operating very tall doors that only open to their full height occasionally. The Mid-Stop does not effect the operator when closing. To operate door to full open position from mid-stop, press open button again.

NOTE: Setting of the MID-STOP should only be performed AFTER Travel Limits have been set and door has been cycled fully open and then fully closed.

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press the CLOSE  to close the door to the down limit.
- 3) Press SCROLL  until display reads "MID-STOP >CLR" **Figure 14.**

: If the display reads MID-STOP > SET at this point, first clear the MID-STOP as described below then repeat steps 1-3 and continue.

- 4) Press the OPEN  to open the door to desired mid-stop height.
- 5) Press SET/CLEAR  until the display reads "MID-STOP > SET"
- 6) Press CAL/RUN  to return to run mode.

To CLEAR the Limit

- 1) Press CAL/RUN  to enter calibration mode.
- 3) Press SCROLL  until display reads "MID-STOP >SET"
- 5) Press SET/CLEAR  until the display reads "MID-STOP > CLR"
- 8) Press CAL/RUN  to return to run mode.

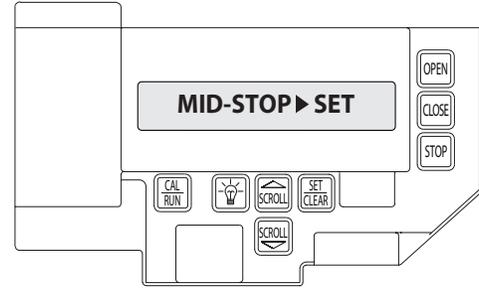


Figure 14

**AN ALTERNATE METHOD FOR SETTING LIMITS
USING THE WALL BUTTONS IS ON PAGE 6.5**

Monitored Reversing Devices

ODC Safe-T-Beams® (OPTIONAL)

- 1) If operator is in RUN mode, press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  (up or down) until display reads "ODC STB>ON" or "ODC STB>OFF" **Figure 15**.
- 3) Press SET/CLEAR  key to toggle between ON and OFF.
- 4) Press SCROLL  (up or down) to shift to a new function and lock setting.
- 5) Press CAL/RUN  to return to run mode.

⚠ WARNING: Photocell systems provide entrapment protection when mounted near the doorway in such a way that the lower portion of an individual's leg will break the photocell beam during normal walking through the doorway. If an alternative mounting location is chosen, it must be approved by the facility owner.

Current UL Approved Monitored Reversing Devices

- 1) MillerEdge ME and MT series monitored edge sensors used in combination with Timer-Close Module P/N OPABTCX.S.
- 2) MillerEdge ME and MT series monitored edge sensors used in combination with MillerEdge Signature Module SM-101. (Direct connect through STB inputs).
- 3) Safe-T-Beam® Monitored Photocells from The Genie® Company, P/N 38176R.
- 4) Series II Safe-T-Beam® Monitored Photocells P/N OPAKPE.S.
- 5) NEMA4 Series II Safe-T-Beam®, Monitored Photocells P/N OPAKPEN4GX.S.

NOTE: Installation of Series II Monitored Photocells DOES NOT make the unit legal for residential use. The Genie® Company strictly prohibits any installation of a commercial unit in any residentially zoned construction.

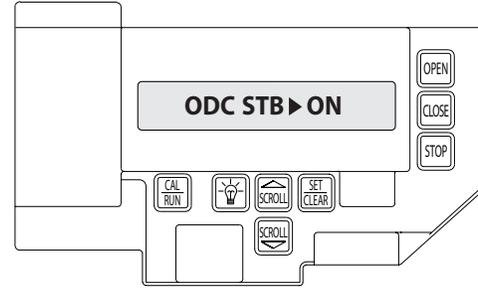
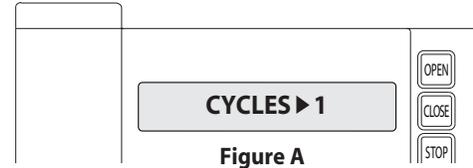


Figure 15

Section 7: Special Operator Features (No user input)

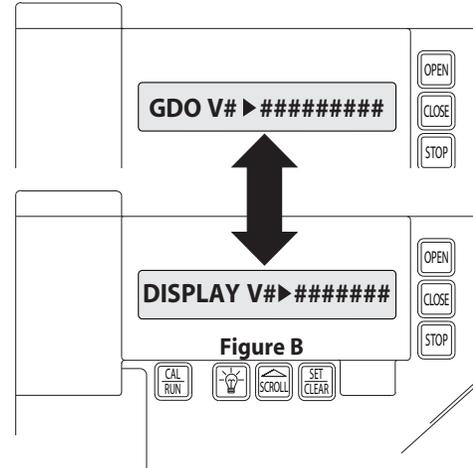
Operator Cycle Count

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "CYCLES>1,2,3 etc. where the number is the number of open/close cycles the operator has performed. **Figure A.**
- 3) Press CAL/RUN  to return to run mode.



GDO and Display Firmware

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "GDO V# > #####." **Figure B.** This display will cycle between the version number of the current GDO firmware and the current Display Firmware.
- 3) Press CAL/RUN  to return to run mode.



Operator Type Fig. 3

These operators are available for use in jackshaft or trolley configurations. The same control board is used for either configuration, however the control board must be set for the appropriate GDO configuration. A board set for trolley mode will not work in a jackshaft operator and vice-versa.

NOTE: The GDO type is factory set. The installer should not have to set this feature. However, if the GDO type is inadvertently changed, or if a board needs to be replaced in the field, follow these instructions to set GDO type.

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "GDO TYPE > ."
This will display the current GDO type.
- 3) Press SET/CLEAR  until display indicates correct GDO type (J-SHAFT or TROLLEY)
- 4) Press CAL/RUN  to return to run mode.

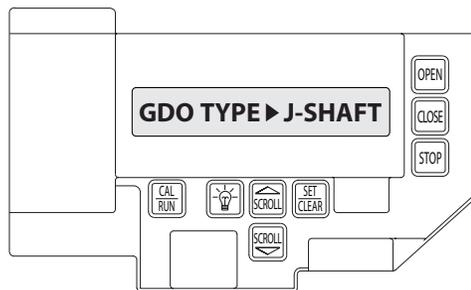


Figure 3

Section 8: Troubleshooting

Display Operation in Run Mode

These operators display their status on the integrated display. Each time the operator runs, stops, reverses or refuses to run, the display will indicate why the action did, or did not, take place.

Once an error code has been generated, the operator will continue to display the error code while the operator is not running. This error code can be cleared by pressing the STOP button or STOP key on the keypad. The error code will automatically clear when the operator stops at the down limit. Error codes will continue to be stored in the operator's Error Code Memory after they have been cleared from the display in the Run Mode.

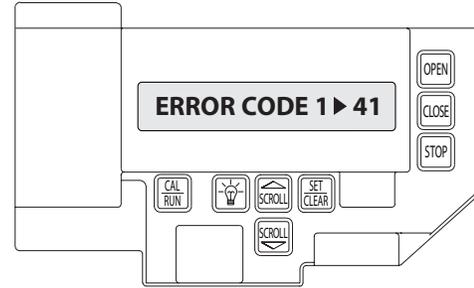


Figure 1

Error Codes

To aid in troubleshooting problems, these operators include an error code memory that stores the last 10 error events. These codes are stored with or without power. The last error code detected is also displayed on the LCD until the stop button or key is pressed or the operator stops at the down limit.

The error code memory stores the last 10 error codes in sequence. Once 10 codes are stored, the oldest code is erased to make room for the newest code. These codes are displayed in calibration mode. The display will flash the number of the error code and the 2-digit error code followed by a description of the error code. **Fig. 1 & 2.**

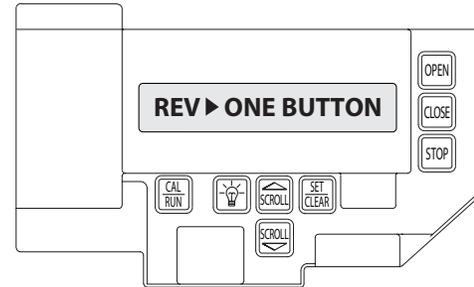


Figure 2

Error Codes (continued)

To view the error code memory:

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "ERROR CODE 1 >".
 - The display will begin flashing the error code number and 2-digit error code followed by its description.
 - Reminder: Error code number 1 is the latest code generated.
- 3) Press SET/CLEAR . The display will now read "ERROR CODE 2 > ." (This is the error code which was generated before error code 1.)
- 4) Repeat step 3 until all 10 error codes have been displayed or move on to step 5 when ready.
- 5) Press CAL/RUN  to return to run mode.

NOTE: For all error codes see Appendix C, Sections 10.11 - 10.12.

Run Codes

The operators also include a run code memory that stores the last 10 run events. These codes are stored with or without power. Each time the operator runs or stops, it generates a code that it stores in this memory (Why the operator ran or stopped). Used together with the error code memory, it becomes a powerful troubleshooting aid.

The run code memory stores the last 10 codes in sequence. Once 10 codes are stored, the oldest code is erased to make room for the newest code. These codes are displayed in calibration mode. The display will flash the number of the run code and the 2-digit run code followed by a description of the run code. **Fig. 3 & 4.**

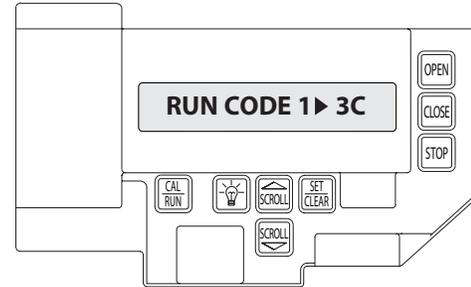


Figure 3

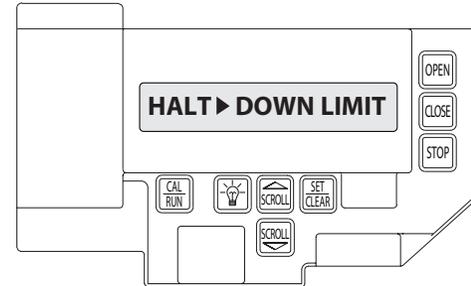


Figure 4

Run Codes (continued)

To view the run code memory:

- 1) Press CAL/RUN  to enter calibration mode.
- 2) Press SCROLL  until display reads "RUN CODE 1 > ."
 - The display will begin flashing the run code number and code followed by its description.
 - Remember: run code number 1 is the latest code generated.
- 3) Press SET/CLEAR . The display will now read "RUN CODE 2 > ."
 (This is the run code which was generated before run code 1.)
- 4) Repeat step 3 until all 10 run codes have been displayed or move on to step 5 when ready.
- 5) Press CAL/RUN  to return to run mode.

NOTE: For all run codes see Appendix C, Section 10.10.

TROUBLESHOOTING EXAMPLE USING RUN AND ERROR CODE MEMORIES. Fig. 5

1. In Calibration Mode, display and write down each Run Code and Error Code stored in memory.
2. List as shown in Fig. 5.
3. Refer to Appendix C to interpret the codes.

In this example, the operator was opened using the OPEN key on the keypad and stopped at the up limit. The OPEN wall button was then activated, causing the "6D" code to be generated since the operator could not open when it is already at the up limit. The CLOSE wall button was then activated, causing the operator to close. While closing, the Normally-Open (N-O) Safety Input was activated, causing the operator to stop and then reverse, stopping at the up limit.

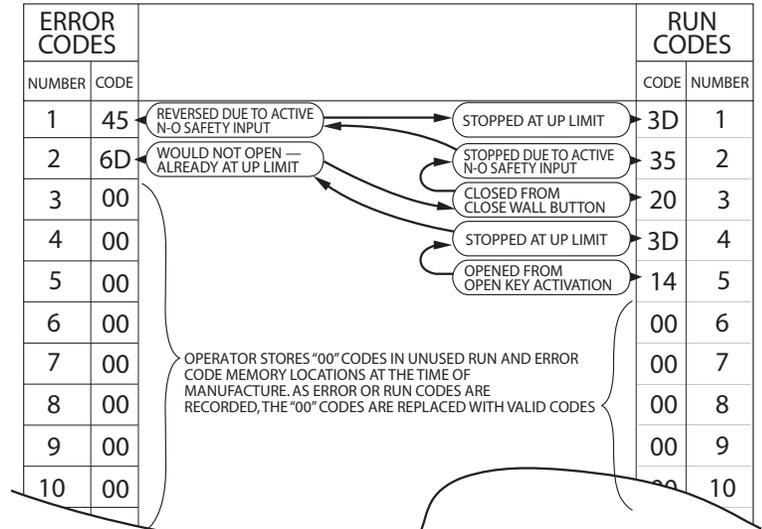
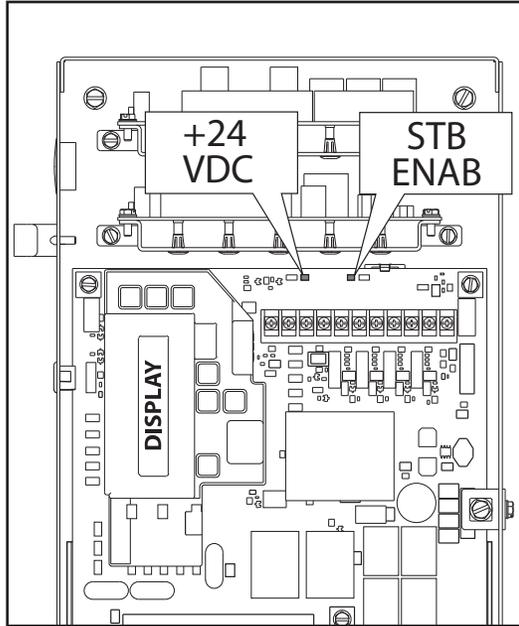


Figure 5

LED Indicators Fig. 6

GH™ operators include a self-diagnostic circuit board using troubleshooting LED indicators to signal the technician of a problem.

Figure 6



TROUBLESHOOTING LED's

STB ENABLE	NORMALLY ON - STB ENABLED	OFF - STB DISABLED
+ 24 VOLTS DC	NORMALLY ON - POWER AVAILABLE	OFF - CHECK AC POWER SUPPLY CHECK FUSES

Safe-T-Beam® Monitored Photocell Self-diagnostic Troubleshooting Chart

SOURCE (RED LED)	SENSOR (GREEN LED)	INDICATED CONDITION	REQUIRED ACTION
● ON	● ON	NORMAL OPERATION	NONE REQUIRED
○ OFF	○ OFF	1. POWER HEAD NOT POWERED 2. WIRING FROM POWER HEAD BAD	1. CHECK BREAKERS, FUSES, PLUGS 2. CHECK WIRING FOR OBVIOUS SHORTS
○ OFF	● ON	1. WIRING TO SOURCE MISSING OR BAD 2. POWER HAS BEEN INTERRUPTED	1. CHECK WIRING 2. REMOVE POWER AND REAPPLY
2 BLINKS, PAUSE (REPEAT)	● ON	1. BEAM NOT ALIGNED 2. BEAM OBSTRUCTED 3. SENSOR DEFECTIVE	1. CHECK ALIGNMENT 2. CHECK FOR OBSTRUCTION 3. CALL CUSTOMER SERVICE
2 BLINKS, PAUSE (REPEAT)	○ OFF	1. WIRE TO SENSOR MISSING OR BAD 2. SENSOR DEFECTIVE	1. CHECK WIRING 2. CALL CUSTOMER SERVICE
3 BLINKS, PAUSE (REPEAT)	● ON	1. SENSOR RECEIVING INTERFERENCE	1. ATTEMPT TO DETERMINE SOURCE OF INTERFERENCE 2. CALL CUSTOMER SERVICE
4 BLINKS, PAUSE (REPEAT)	● ON	1. SOURCE NOT SENDING PULSES 2. SOURCE DEFECTIVE	1. CALL CUSTOMER SERVICE 2. CALL CUSTOMER SERVICE

⚠ WARNING: ACTUATING THE OPERATOR BY USING CONSTANT CONTACT ON THE CLOSE BUTTON WILL OVERRIDE EXTERNAL REVERSING DEVICES, INCLUDING PHOTOCELLS.

⚠ WARNING: OVERHEAD DOOR CORPORATION RECOMMENDS THAT LINE VOLTAGE WIRING BE PERFORMED BY A QUALIFIED ELECTRICIAN. SEE SECTION 5 FOR ADDITIONAL WIRING INSTRUCTIONS.

Section 9: Service and Maintenance

Maintenance Schedule

The following table provides a schedule of recommended Service and Maintenance items to be completed by a trained service representative.

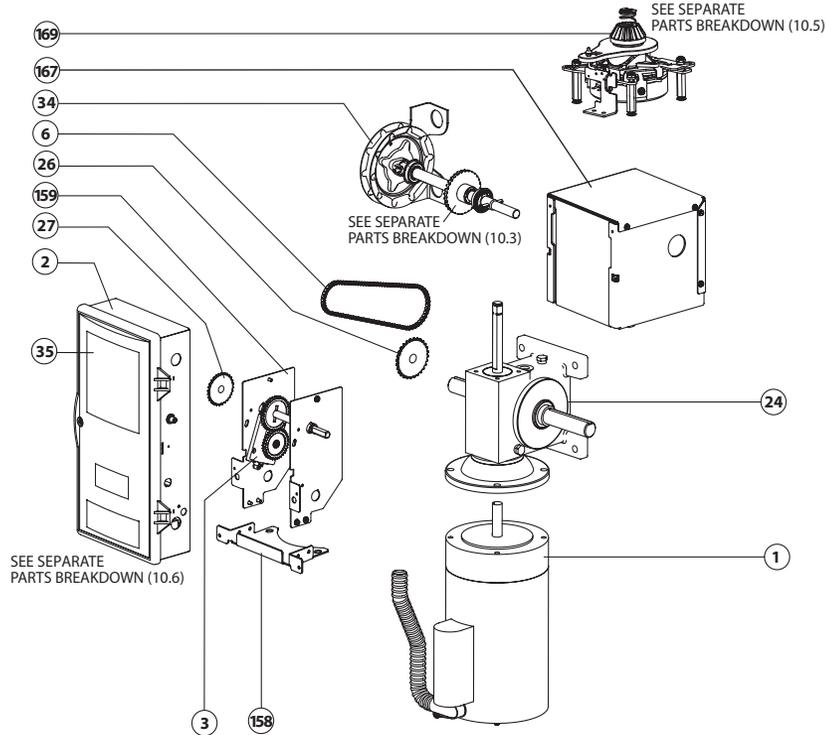
⚠ CAUTION: Failure to perform the recommended Service & Maintenance may result in premature failure of the operator.

SERVICE ITEM	SERVICE INTERVAL (FREQUENCY)			
	MONTHLY	EVERY 6 MO. OR 5,000 CYCLES	EVERY 12 MO. OR 10,000 CYCLES	EVERY 36 MO. OR 30,000 CYCLE
MANUAL OPERATION OF DOOR		●		
* PHOTOCCELL/ SENSING EDGE OPERATION	●			
OPTIONAL CLUTCH ADJUSTMENT			●	
CHECK FOR LOSE OR MISSING HARDWARE			●	
CHECK LIMIT POSITION				●
GEAR TRAIN WEAR				●

* If Installed.

Section 10: Appendix A

Basic Operator Parts



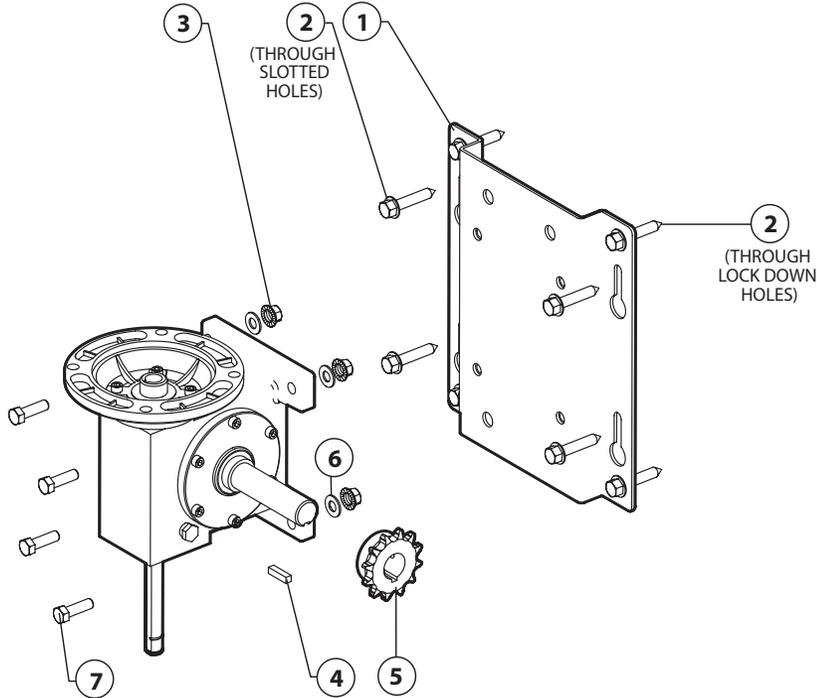
PARTS LIST		
ITEM NO.	PART NUMBER	DESCRIPTION
1	111502**	ELECTRIC MOTOR
2	111794**	ELECTRIC BOX ASSEMBLY
3	111421.0003	LIMIT MODULE
6	086565.1032.S	CHAIN
24	111503**	GEARBOX
26	111537.0001	LIMIT SPROCKET, OUTPUT
27	111536.0001	LIMIT SPROCKET, INPUT
34	111019**	HOIST SHAFT KIT
35	SEE PG 10.6	ELECTRICAL BOX COVER
159	111602.0001	LIMIT ENCLOSURE ASSEMBLY
167	111597.0001	BRAKE ENCLOSURE ASSEMBLY
169	111861.0001.S	BRAKE/RELEASE KIT

NS=NOT SHOWN

** CONTACT DEALER FOR PROPER PART
BASED ON YOUR SPECIFIC MODEL.

Section 10: Appendix A

Wall Mount Kit (Indirect Couple)



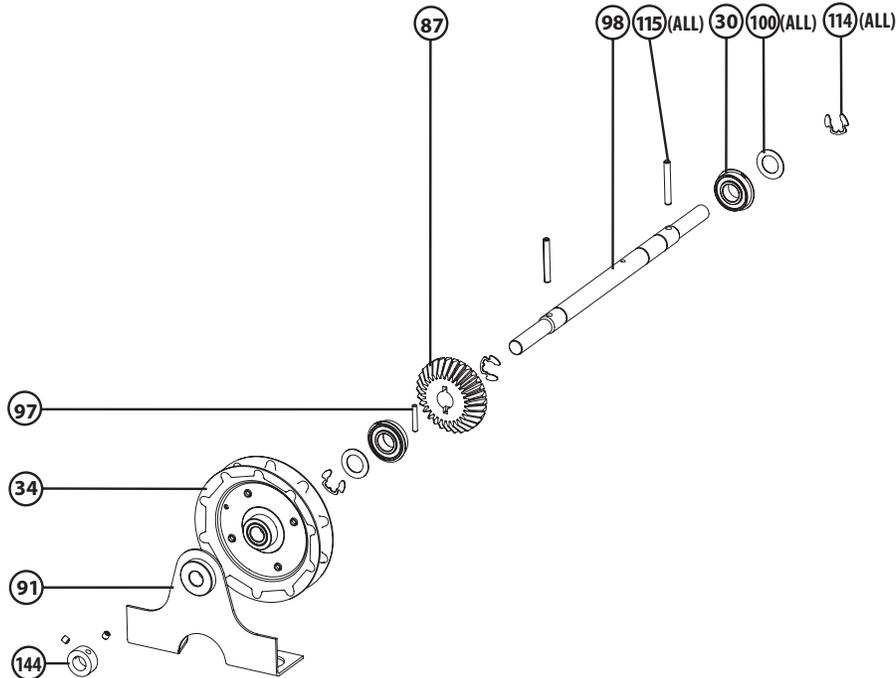
PARTS LIST		
ITEM NO.	PART NUMBER	DESCRIPTION
1	111551.0001	WALL MOUNT BRACKET
2	111632.0001	LAG SCREW
3	086480.2416	HEX NUT
4	080340.0015	KEY
5	086446.1216	SPROCKET ASSY
6	080302.2626	FLAT WASHER
7	080105.0610	BOLT

NS=NOT SHOWN

** CONTACT DEALER FOR PROPER PART
BASED ON YOUR SPECIFIC MODEL.

Appendix A (continued)

Basic Hoist Shaft Parts



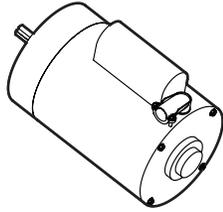
PARTS LIST		
ITEM NO.	PART NUMBER	DESCRIPTION
144	604297.3062	SET COLLAR
91	110411.0001	CHAIN GUARD ASSEMBLY
34	110872.0001	HANDWHEEL
97	110881.0001	DOWEL PIN
87	111552.0001	BEVEL GEAR, 30T
98	111529.0001	HOIST SHAFT
115	110313.0010	SPRING PIN
30	110813.0001	BEARING
100	110819.0001	FLAT WASHER
114	111382.0003	E-RING, 744"

NS=NOT SHOWN

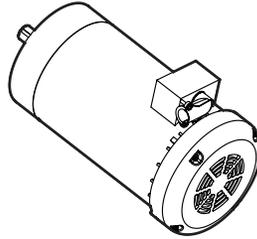
** CONTACT DEALER FOR PROPER PART
BASED ON YOUR SPECIFIC MODEL.

Appendix A (continued)

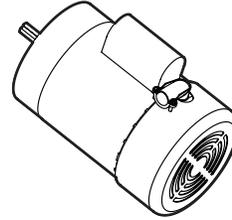
Motor Options



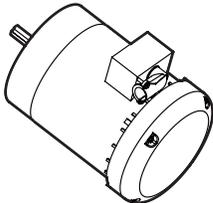
111502.0001—1/2HP, 1 PH, ODP
 111502.0002—3/4HP, 1 PH, ODP
 111502.0003—1HP, 1 PH, ODP
 111502.0004—1/2HP, 3 PH, ODP
 111502.0005—3/4HP, 3 PH, ODP
 111502.0006—1HP, 3 PH, ODP
 111502.0007—1/2HP, 575V, ODP
 111502.0008—3/4HP, 575V, ODP
 111502.0009—1HP, 575V, ODP



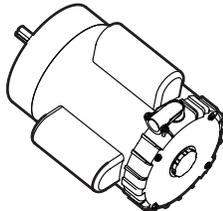
111548.0001—3HP, 3 PH, FC
 111548.0002—3HP, 575V, FC



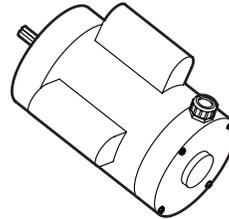
111694.0001—1/2HP, 1 PH, TEFC
 111694.0002—1HP, 1 PH, TEFC



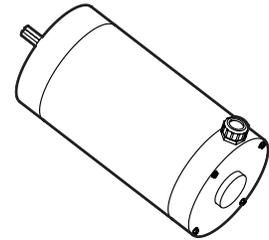
111695.0001—1/2HP, 3 PH, TEFC
 111695.0002—1HP, 3 PH, TEFC
 111695.0003—1HP, 575V, TEFC



111696.0001—1/2HP, 1 PH, TENV
 111696.0002—1/2HP, 3 PH, TENV
 111696.0003—1HP, 3 PH, TENV
 111696.0004—1HP, 575V, TENV



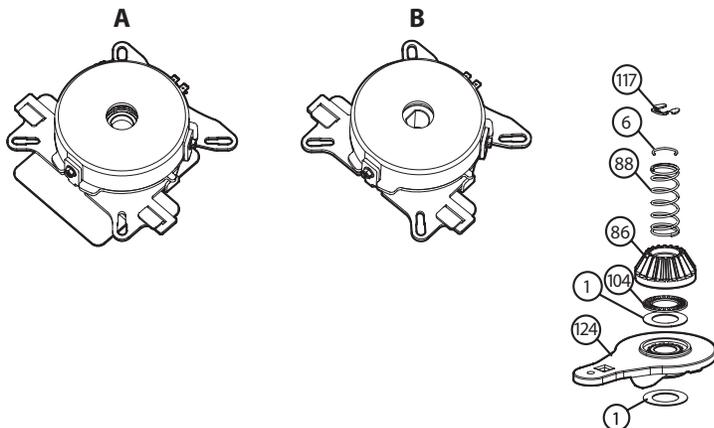
111697.0001—1/2HP, 1 PH, N4
 111697.0002—1HP, 1 PH, N4
 111697.0003—1/2HP, 3 PH, N4
 111697.0004—1HP, 3 PH, N4
 111697.0004—1HP, 575V, N4



111698.0001—3HP, 3 PH, N4, GH
 111698.0002—3HP, 575V, N4, GH

Appendix A (cont')

Basic Brake/Release Parts



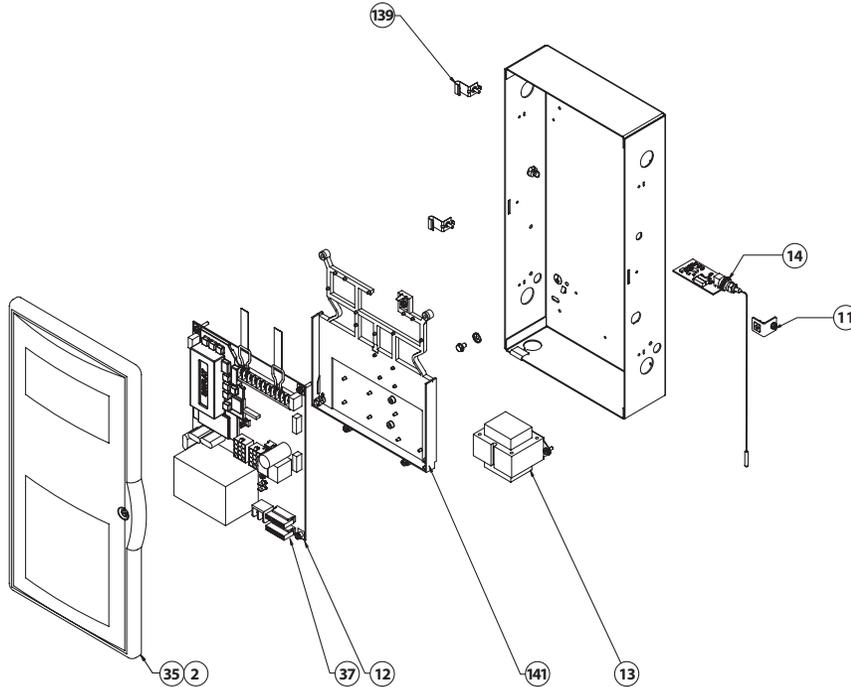
PARTS LIST		
ITEM NO.	PART NUMBER	DESCRIPTION
A	111861.0001	BRAKE ASSEMBLY (STANDARD)
B	111862.0001	BRAKE ASSEMBLY (3 HP)
117	111382.0002	E-RING
6	111600.0001	CONSTANT SECTION RING
88	111555.0001	SPRING
86	111539.0001	PINION GEAR (STANDARD)
	111553.0001	BEVEL GEAR (3 HP)
104	111402.0001	THRUST BEARING
1	111403.0001	THRUST WASHER
124	111599.0001	BRAKE RELEASE

NS=NOT SHOWN

** CONTACT DEALER FOR PROPER PART
BASED ON YOUR SPECIFIC MODEL.

Appendix A (cont')

Basic Electric Box Repair Parts



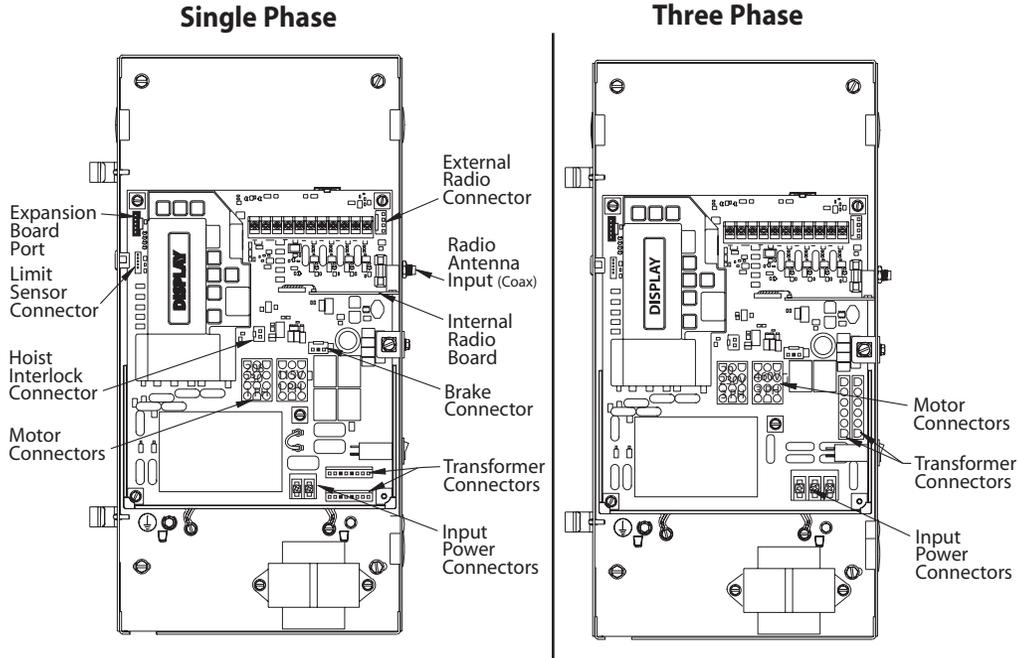
PARTS LIST		
ITEM NO.	PART NUMBER	DESCRIPTION
2	110505.0003	ELECTRICAL BOX
11	110870.0001	ELECTRIC BOX LATCH
12	112357.0001.S	KIT, PCB, 1PH, CONT, UL
	112357.0002.S	KIT, PCB, 1PH, RELAY, UL
	112357.0003.S	KIT, PCB, 3PH, CONT, UL
	112357.0004.S	KIT, PCB, 575V, UL
13	111087.0001	XFMR, 120/208/240V
	111087.0002	XFMR, 208/240/480V
	111087.0003	XFMR, 575V
14	36163R	RADIO RECEIVER ASSEMBLY
35	111591.0001	ELECTRICAL BOX COVER ASSY
NS	110100**	MOTOR CIRCUIT BREAKER
NS	111781.0001.S	INTERLOCK SWITCH
139	110423.0001	ELECTRIC BOX COVER HINGE
NS	111518.0001.S	ELECTRIC BOX COVER BRACKET
141	111101.0001	MAIN CIRCUIT BOARD INSULATOR

NS=NOT SHOWN

** CONTACT DEALER FOR PROPER PART
BASED ON YOUR SPECIFIC MODEL.

Appendix A (cont')

Basic Electric Box Layout



Section 10: Appendix C

Screw Terminal Assignments

INPUT		FUNCTION	CONNECTION TYPE
11-POSITION TERMINAL BLOCK INSIDE ELECTRIC BOX	OPEN	Causes door to open if not at Up Limit. Causes a closing door to reverse.	Normally-Open Dry Contact to GND.
	CLOSE	Causes door to close if not at Down Limit.	Normally-Open Dry Contact to GND.
	STOP	Causes a moving door to stop. Prevents the operator from running.	Normally-Closed Dry Contact to GND.
	GND	Common ground connection for Open, Close, Stop & 1-Btn Inputs.	
	1-BTN	Causes door to open if not at Up Limit or Mid-Stop Limit. Causes door to close if at Up Limit or Mid-Stop Limit. Causes door to stop if opening. Causes a closing door to reverse.	Normally-Open Dry Contact to GND.
	ODC STB	Reverses a closing door if photocell beam is blocked. NOTE: STB's must be enabled in Calibration Mode.	ODC Series II Safe-T-Beams® ONLY to these inputs. (not polarity sensitive)
	ODC STB	Reverses a closing door if photocell beam is blocked. NOTE: STB's must be enabled in Calibration Mode.	ODC Series II Safe-T-Beams® ONLY to these inputs. (not polarity sensitive)
	N-O REVERSE	Causes a closing door to reverse. NOTE: Will not open a stopped door.	Normally-Open 2-Wire Non-Monitored Edge Sensor. (not polarity sensitive)
	N-O REVERSE	Causes a closing door to reverse. NOTE: Will not open a stopped door.	Normally-Open 2-Wire Non-Monitored Edge Sensor. (not polarity sensitive)
2-POSITION TERMINAL BLOCK (INSIDE ELECTRIC BOX)	L1 / L1	Power to operator.	120VAC: Connect to Line (Hot) / 240VAC: Connect to Line 1.
	N / L2	Power to operator.	120VAC: Connect to Neutral / 240VAC: Connect to Line 2.
	EXT INTLK	Causes a moving door to stop. Prevents the operator from running when contact is open. Operates even if microcontroller is non-functional.	Normally-Closed dry contacts. (board will energize these contacts at nominal +24VDC).
	EXT INTLK	Causes a moving door to stop. Prevents the operator from running when contact is open. Operates even if microcontroller is non-functional.	Normally-Closed dry contacts. (board will energize these contacts at nominal +24VDC).

Other Connections

RADIO AND ACCESSORIES PIGTAIL	PWR	Power for radio & other accessories. +20 to +40VDC, fused at 250mA (F1).	Connect to radio or other accessory's power input.
	RAD (Radio Input Control)	Causes door to open if not at Up Limit or Mid-Stop Limit. Causes door to close if at Up Limit or Mid-Stop Limit. Causes a closing door to reverse.	Connect to radio or other accessory's signal (output).
	GND	Common ground connection for PWR and RAD terminals.	Connect to radio or other accessory's ground input.
PLUG CONNECTIONS INSIDE ELECTRIC BOX	EXPANSION PORT	Connects accessory modules to operator.	Accessory Module Ribbon Cable.
	TRANSFORMER	Connects main transformer to control board.	Transformer Plug.
	BRAKE	Connects brake solenoid to control board.	Brake Solenoid Plug.
	MOTOR	Connects motor and capacitor to control board.	Motor Plug.
	HOIST INTLK	Causes moving door to stop. Prevents the operator from running. Operates even if microcontroller is non-functional.	Hoist Interlock Plug or Jumper.
	LIMIT SENSOR	Causes door to stop at top and bottom of normal travel.	Limit Sensor Plug.

Section 10: Appendix D

Run Code Displays

Condition Code	DISPLAY	Condition Code Description
0C	IDLE > DOWN LIMIT	STANDING BY AT DOWN LIMIT (NOTE: THIS MESSAGE IS DISPLAYED IF BOTH LIMITS ARE ACTIVE)
0D	IDLE > UP LIMIT	STANDING BY AT UP LIMIT
0E	IDLE > MID STOP	STANDING BY AT MID-STOP LIMIT
0F	IDLE > NO LIMIT	STANDING BY BETWEEN LIMITS
10	OPENING > OPEN BTN	OPENING FROM OPEN BUTTON
11	OPENING > ONE BTN	OPENING FROM 1 BUTTON
12	OPENING > RADIO	OPENING FROM RADIO
13	OPENING > AUX OPEN	OPENING FROM AUXILIARY OPEN INPUT
14	OPENING > OPEN KEY	OPENING FROM KEYPAD OPEN KEY
20	CLOSING > CLOSE PB	CLOSING FROM CLOSE BUTTON
21	CLOSING > ONE BTN	CLOSING FROM 1 BUTTON
22	CLOSING > RADIO	CLOSING FROM RADIO
24	CLOSING > CLOSE KP	CLOSING FROM KEYPAD CLOSE KEY
2A	CLOSING > TCM CLS	CLOSING FROM TIMER CLOSE MODULE
2B	CLOSING > FDM CLS	CLOSING FROM FORE DOOR MODULE
30	HALT > WALL BUTTON	GDO STOPPED BECAUSE STOP OR OPEN BUTTON WAS ACTIVATED, POSSIBLY STARTING A REVERSAL
31	HALT > ONE BUTTON	GDO STOPPED BECAUSE 1 BUTTON WAS ACTIVATED, POSSIBLY STARTING A REVERSAL
32	HALT > RADIO	GDO STOPPED BECAUSE RADIO INPUT WAS ACTIVATED, STARTING A REVERSAL
33	HALT > AUX. OPEN	GDO STOPPED BECAUSE AUXILIARY OPEN INPUT WAS ACTIVATED, STARTING A REVERSAL
34	HALT > KEYPAD KEY	GDO STOPPED BECAUSE KEYPAD STOP OR OPEN KEY WAS ACTIVATED, POSSIBLY STARTING A REVERSAL
35	HALT > N-O SAFETY	GDO STOPPED BECAUSE N-O REVERSING INPUT WAS ACTIVATED, STARTING A REVERSAL
36	HALT > ODC STB	GDO STOPPED BECAUSE ODC STB WAS BLOCKED, STARTING A REVERSAL
37	HALT > N-C SAFETY	GDO STOPPED BECAUSE N-C REVERSING INPUT WAS ACTIVATED, STARTING A REVERSAL
38	HALT > MON. EDGE	GDO STOPPED BECAUSE MONITORED EDGE SENSOR INPUT WAS ACTIVATED, STARTING A REVERSAL
39	HALT > DOOR FORCE	GDO STOPPED BECAUSE THE FORCE REQUIRED TO OPERATE THE DOOR WAS TOO HIGH, POSSIBLY STARTING A REVERSAL
3A	HALT > LOSS OF C/C	GDO STOPPED BECAUSE CONSTANT CONTACT ON CONTROL REMOVED BEFORE REACHING A LIMIT, POSSIBLY STARTING A REVERSAL
3B	HALT > SHUTDOWN	GDO STOPPED BECAUSE THE GDO DETECTED A FAULT SUCH AS AN OPEN INTERLOCK, OVERHEATED MOTOR, ETC.
3C	HALT > DOWN LIMIT	GDO STOPPED BECAUSE IT REACHED THE DOWN LIMIT
3D	HALT > UP LIMIT	GDO STOPPED BECAUSE IT REACHED THE UP LIMIT
3E	HALT > MID STOP	GDO STOPPED BECAUSE IT REACHED THE MID-STOP LIMIT
3F	HALT > MODULE FAIL	GDO STOPPED BECAUSE AN EXPANSION MODULE WAS NOT WORKING PROPERLY
40	REV > OPEN BUTTON	GDO REVERSED BECAUSE THE OPEN BUTTON WAS ACTIVATED
41	REV > ONE BUTTON	GDO REVERSED BECAUSE THE 1 BUTTON WAS ACTIVATED
42	REV > RADIO	GDO REVERSED BECAUSE THE RADIO INPUT WAS ACTIVATED
43	REV > AUX OPEN	GDO REVERSED BECAUSE THE AUXILIARY OPEN INPUT WAS ACTIVATED
44	REV > OPEN KEY	GDO REVERSED BECAUSE THE KEYPAD OPEN KEY WAS ACTIVATED
45	REV > N-O SAFETY	GDO REVERSED BECAUSE THE N-O REVERSING INPUT WAS ACTIVATED

Appendix D (cont')

Error Code Displays

Condition Code	DISPLAY	Condition Code Description
46	REV > ODC STB	GDO REVERSED BECAUSE THE ODC STB WAS BLOCKED
47	REV > N-C SAFETY	GDO REVERSED BECAUSE THE N-C REVERSING INPUT WAS ACTIVATED
48	REV > MON. EDGE	GDO REVERSED BECAUSE THE MONITORED EDGE SENSOR WAS ACTIVATED
49	REV > DOOR FORCE	GDO REVERSED BECAUSE THE FORCE REQUIRED TO CLOSE THE DOOR WAS TOO HIGH
4A	REV > LOSS OF C/C	GDO REVERSED BECAUSE CONSTANT CONTACT ON THE CONTROL WAS REMOVED BEFORE REACHING THE DOWN LIMIT
4B	REV > MAX RUN TMR	GDO REVERSED BECAUSE THE CLUTCH SLIPPED OR SOME OTHER FAULT OCCURRED THAT ALLOWED THE GDO TO RUN TOO LONG
4F	REV > EXP MOD FAIL	GDO REVERSED BECAUSE AN EXPANSION MODULE WAS NOT WORKING PROPERLY
50	STOP > HOT MOTOR	GDO STOPPED BECAUSE THE MOTOR WAS OVERHEATED
51	STOP > OPEN MRT	GDO STOPPED BECAUSE THE CLUTCH SLIPPED OR SOME OTHER FAULT OCCURRED THAT ALLOWED THE GDO TO RUN OPEN TOO LONG
52	STOP > CLOSE MRT	GDO STOPPED BECAUSE THE CLUTCH SLIPPED OR SOME OTHER FAULT OCCURRED THAT ALLOWED THE GDO TO RUN DOWN TOO LONG
57	STOP > OPEN INTLK	GDO STOPPED BECAUSE THE HOIST INTERLOCK OR EXTERNAL INTERLOCK IS OPEN
58	STOP > WRONG GDO	GDO STOPPED BECAUSE THE BOARD IS SET FOR JACKSHAFT MODE, BUT INSTALLED IN A TROLLEY OPERATOR
59	STOP > DOOR FORCE	GDO STOPPED BECAUSE THE FORCE REQUIRED TO OPEN THE DOOR WAS TOO HIGH
5A	STOP > WRONG LIMIT	GDO STOPPED BECAUSE THE UP LIMIT ACTIVATED WHEN CLOSING OR THE DOWN LIMIT ACTIVATED WHEN OPENING
5B	STOP > WRONG DIR	GDO STOPPED BECAUSE THE DOOR MOVED IN THE WRONG DIRECTION
5C	STALL > DOWN LIMIT	GDO STOPPED BECAUSE IT COULDN'T LEAVE THE DOWN LIMIT DUE TO A SLIPPING CLUTCH OR OTHER PROBLEM
5D	STALL > UP LIMIT	GDO STOPPED BECAUSE IT COULDN'T LEAVE THE UP LIMIT DUE TO A SLIPPING CLUTCH OR OTHER PROBLEM
5E	STALL > MID-STOP	GDO STOPPED BECAUSE IT COULDN'T LEAVE THE MID-STOP LIMIT DUE TO A SLIPPING CLUTCH OR OTHER PROBLEM
60	CHECK STOP BTN	GDO WON'T RUN BECAUSE THE STOP BUTTON IS ACTIVE
61	TCM DISABLED	TIMER CLOSE WON'T WORK BECAUSE NO SAFETIES ARE ENABLED
62	NO RADIO >> C/C	RADIO INPUT WON'T WORK WITH OPEN OR CLOSE FUNCTION IN CONSTANT CONTACT MODE
63	CHECK AUX OPEN	GDO WON'T CLOSE BECAUSE AUXILIARY OPEN INPUT IS ACTIVE
64	CHECK STOP KEY	GDO WON'T RUN BECAUSE THE KEYPAD STOP KEY IS ACTIVE
65	CHECK N-O SAFETY	GDO WON'T CLOSE BECAUSE THE N-O REVERSING IS ACTIVE
66	CHECK ODC STB	GDO WON'T CLOSE BECAUSE THE ODC STB IS BLOCKED
67	CHECK N-C SAFETY	GDO WON'T CLOSE BECAUSE THE N-C REVERSING INPUT IS ACTIVE
68	CHECK MON. EDGE	GDO WON'T CLOSE BECAUSE THE MONITORED EDGE SENSOR IS ACTIVE
69	OVERHEATED MOTOR	GDO WON'T RUN BECAUSE THE MOTOR IS OVERHEATED
6A	POWER WIRING ERROR	GDO WON'T RUN BECAUSE
6B	FIRE DOOR SHTDN	GDO WON'T RUN BECAUSE OF LOSS OF POWER
6C	NO RUN > DOWN LIM	GDO WON'T CLOSE BECAUSE ITS ALREADY AT THE DOWN LIMIT
6D	NO RUN > UP LIMIT	GDO WON'T OPEN BECAUSE ITS ALREADY AT THE UP LIMIT
6E	NO RUN > MID STOP	GDO WON'T RUN BECAUSE ITS AT OR ABOVE THE MID-STOP LIMIT & CAN'T RUN UP & A REVERSING INPUT IS PREVENTING IT FROM CLOSING
6F	EXP MODULE FAIL	GDO WON'T RUN BECAUSE AN EXPANSION MODULE FAILURE IS PREVENTING IT

Appendix D (cont')

Error Codes Displays (continued)

Condition Code	DISPLAY	Condition Code Description
70	BOARD FAILURE 70	CONTROL BOARD FAILURE 70, CONTACT FACTORY TECHNICAL SERVICE DEPT.
71	BOARD FAILURE 71	CONTROL BOARD FAILURE 71, CONTACT FACTORY TECHNICAL SERVICE DEPT.
74	BOARD FAILURE 74	CONTROL BOARD FAILURE 74, CONTACT FACTORY TECHNICAL SERVICE DEPT.
75	BOARD FAILURE 75	CONTROL BOARD FAILURE 75, CONTACT FACTORY TECHNICAL SERVICE DEPT.
76	BOARD FAILURE 76	CONTROL BOARD FAILURE 76, CONTACT FACTORY TECHNICAL SERVICE DEPT.
77	BOARD FAILURE 77	CONTROL BOARD FAILURE 77, CONTACT FACTORY TECHNICAL SERVICE DEPT.
80	BOARD FAILURE 80	CONTROL BOARD FAILURE 80, CONTACT FACTORY TECHNICAL SERVICE DEPT.
81	BOARD FAILURE 81	CONTROL BOARD FAILURE 81, CONTACT FACTORY TECHNICAL SERVICE DEPT.
82	BOARD FAILURE 82	CONTROL BOARD FAILURE 82, CONTACT FACTORY TECHNICAL SERVICE DEPT.
83	BOARD FAILURE 83	CONTROL BOARD FAILURE 83, CONTACT FACTORY TECHNICAL SERVICE DEPT.
84	BOARD FAILURE 84	CONTROL BOARD FAILURE 84, CONTACT FACTORY TECHNICAL SERVICE DEPT.
85	EXP PORT PROBLEM	EXPANSION PORT IS SHORT CIRCUITED, TRY DISCONNECTING EXPANSION MODULES OR CONTACT FACTORY TECHNICAL SERVICE DEPT.
86	BOARD FAILURE 86	CONTROL BOARD FAILURE 86, DISCONNECT EXPANSION MODULES. IF NO CHANGE, CONTACT FACTORY TECHNICAL SERVICE DEPT.
87	IEM FAILURE	RESERVED--NOT CURRENTLY USED
88	TCM FAILURE	TIMER CLOSE MODULE (TCM) HAS FAILED
89	FDM FAILURE	FIRE DOOR MODULE (FDM) HAS FAILED
8A	AOM FAILURE	AUXILIARY OUTPUT MODULE (AOM) HAS FAILED
8B	SPARE MOD FAILURE	RESERVED--NOT CURRENTLY USED
8C	LOW SYSTEM VOLTS	POWER SUPPLY LINE VOLTAGE LOW
8D	HI SYSTEM VOLTS	POWER SUPPLY LINE VOLTAGE HIGH
8E	REV INTERRUPTED	GDO LOST POWER OR ENCOUNTERED ANOTHER PROBLEM DURING THE REVERSAL PROCESS, REVERSAL IS COMPLETING NOW
8F	LIMIT MOD. FAIL	GDO WON'T RUN, LIMIT MODULE HAS FAILED
90	DIAGNOSTIC MODE	GDO IS IN DIAGNOSTIC MODE, NORMAL FUNCTIONS ARE NOT ALLOWED
A0	OPEN BTN BAD > PU	OPEN & CLOSE BUTTONS WON'T WORK, THE OPEN BUTTON WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A1	CLOSE BTN BAD > PU	OPEN & CLOSE BUTTONS WON'T WORK, THE CLOSE BUTTON WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A2	ONE BTN BAD > PU	1 BUTTON WON'T WORK, THE 1 BUTTON WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A3	RADIO BAD > PWR UP	RADIO INPUT WON'T WORK, THE RADIO INPUT WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A4	AUX OPEN BAD > PU	AUXILIARY OPEN INPUT WON'T WORK, THE AUXILIARY OPEN INPUT WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A5	OPEN KEY BAD > PU	KEYPAD OPEN & CLOSE KEYS WON'T WORK, THE OPEN KEY WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A6	CLOSE KEY BAD > PU	KEYPAD OPEN & CLOSE KEYS WON'T WORK, THE CLOSE KEY WAS ACTIVE WHEN THE GDO WAS POWERED-UP
A7	MULT KEYS BAD > PU	1 OR MORE KEYPAD CALIBRATION KEYS WON'T WORK, 1 OR MORE WERE ACTIVE WHEN THE GDO WAS POWERED-UP
AA	TCM BAD > POWER UP	RESERVED--NOT CURRENTLY USED
AB	FDM BAD > POWER UP	RESERVED--NOT CURRENTLY USED
B0	OPENING > XMTR #	OPENING FROM TRANSMITTER # ___
B1	CLOSING > XMTR #	CLOSING FROM TRANSMITTER # ___
B2	HALT > XMTR #	HALT FROM TRANSMITTER # ___
B3	NO XMTR > CC	NO CONTROL FROM TRANSMITTER, CONSTANT CONTACT EMPLOYED AT LOCAL CONTROL



Commercial Operator Limited Warranty

The Genie Company ("Seller") warrants to the original purchaser of the model GH™ Trolley or GH™ Hoist commercial door operator ("Product"), subject to all of the terms and conditions hereof, that the Product and all components thereof will be free from defects in materials and workmanship under normal use for the following period(s), measured from the date of installation:

- Two (2) years or 20,000 cycles, whichever occurs first.

Seller's obligation under this warranty is specifically limited to repairing or replacing, at its option, any part which is determined by Seller to be defective during the applicable warranty period. Any labor charges are excluded and will be the responsibility of the purchaser.

This warranty is made to the original purchaser of the Product only, and is not transferable or assignable. This warranty does not apply to any unauthorized alteration or repair of the Product, or to any Product or component which has been damaged or deteriorated due to misuse, neglect, accident, failure to provide necessary maintenance, normal wear and tear, or acts of God or any other cause beyond the reasonable control of Seller.

THIS WARRANTY IS EXCLUSIVE AND IN LIEU OF ANY OTHER WARRANTIES, EITHER EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE.

IN NO EVENT SHALL SELLER BE RESPONSIBLE FOR, OR LIABLE TO ANYONE FOR, SPECIAL, INDIRECT, COLLATERAL, PUNITIVE, INCIDENTAL OR CONSEQUENTIAL DAMAGES, even if Seller has been advised of the possibility of such damages. Such excluded damages include, but are not limited to, loss of goodwill, loss of profits, loss of use, cost of any substitute product, interruption of business, or other similar indirect financial loss.

Claims under this warranty must be made promptly after discovery, within the applicable warranty period, and in writing to the Seller or to the authorized distributor or installer whose name and address appear below. The purchaser must allow Seller a reasonable opportunity to inspect any Product claimed to be defective prior to removal or any alteration of its condition. Proof of the purchase and/or installation date, and identification as the original purchaser, may be required.

ORIGINAL PURCHASER _____

INSTALLATION ADDRESS _____

SELLER _____

SELLER'S ADDRESS: _____

FACTORY ORDER # _____

DATE OF INSTALLATION: _____

SIGNATURE OF SELLER: _____



COMMERCIAL LINE

One Door Dr.
Mt. Hope, OH 44660